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(54) **HIGHLY-SENSITIVE
DISPLACEMENT-MEASURING OPTICAL
DEVICE**

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filed on Mar. 29, 2002, now Pat. No. 6,753,969.

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(58) **Field of Classification Search** 356/498,
356/499, 505, 506, 521; 250/237 G

See application file for complete search history.

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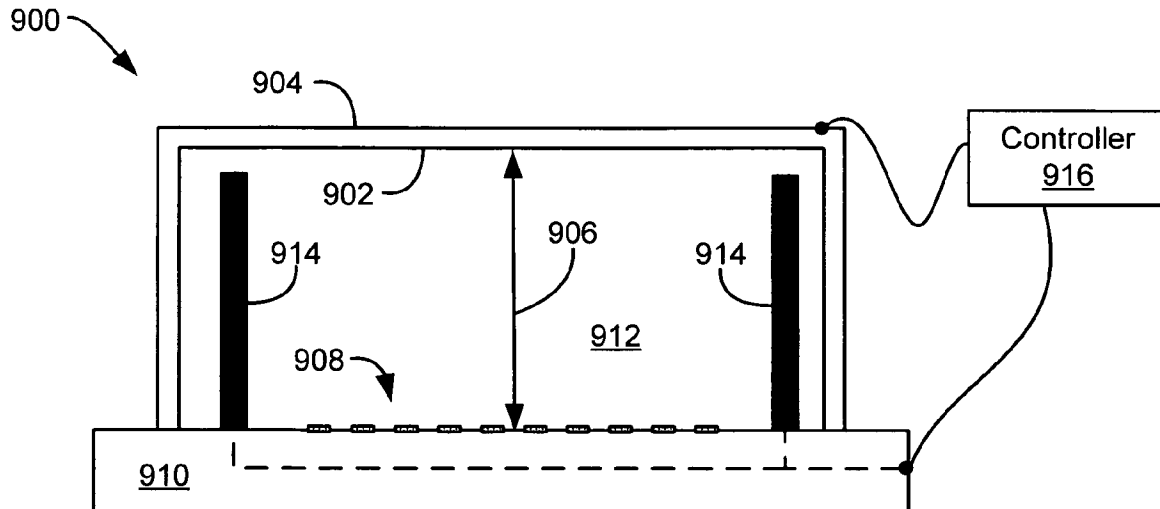
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(57) **ABSTRACT**

Micron-scale displacement measurement devices having enhanced performance characteristics are disclosed. One embodiment of a micron-scale displacement measurement device includes a phase-sensitive reflective diffraction grating for reflecting a first portion of an incident light and transmitting a second portion of the incident light such that the second portion of the incident light is diffracted. The device further includes a mechanical structure having a first region and a second region, the mechanical structure positioned a distance d above the diffraction grating, the second portion of the incident light is reflected off of the first region of the structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light. The device can further include an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

19 Claims, 6 Drawing Sheets



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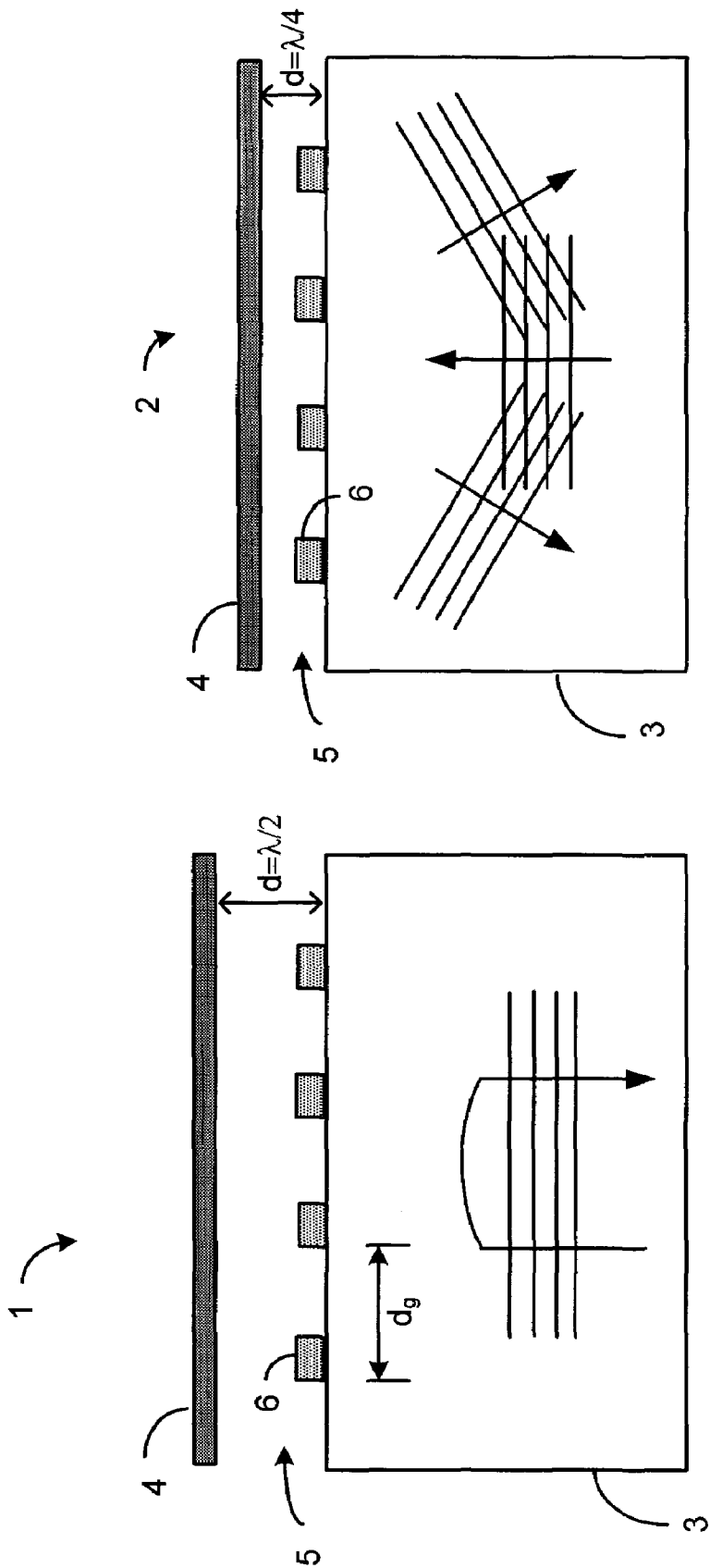
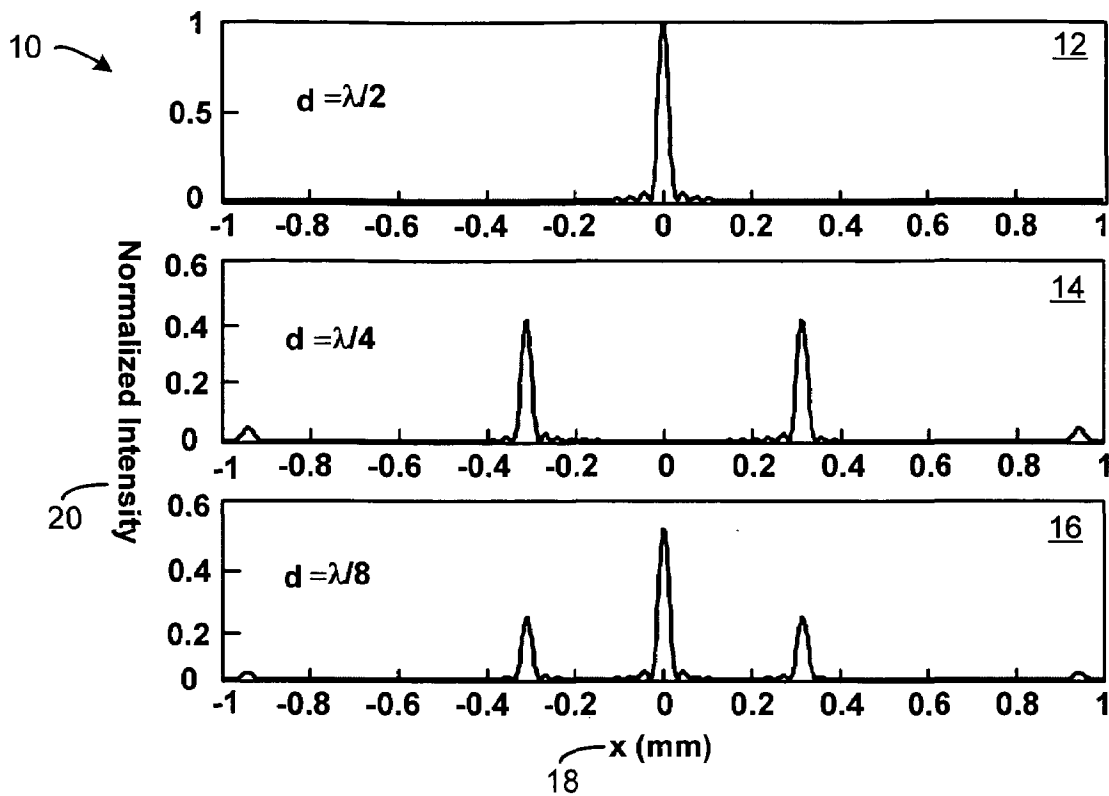
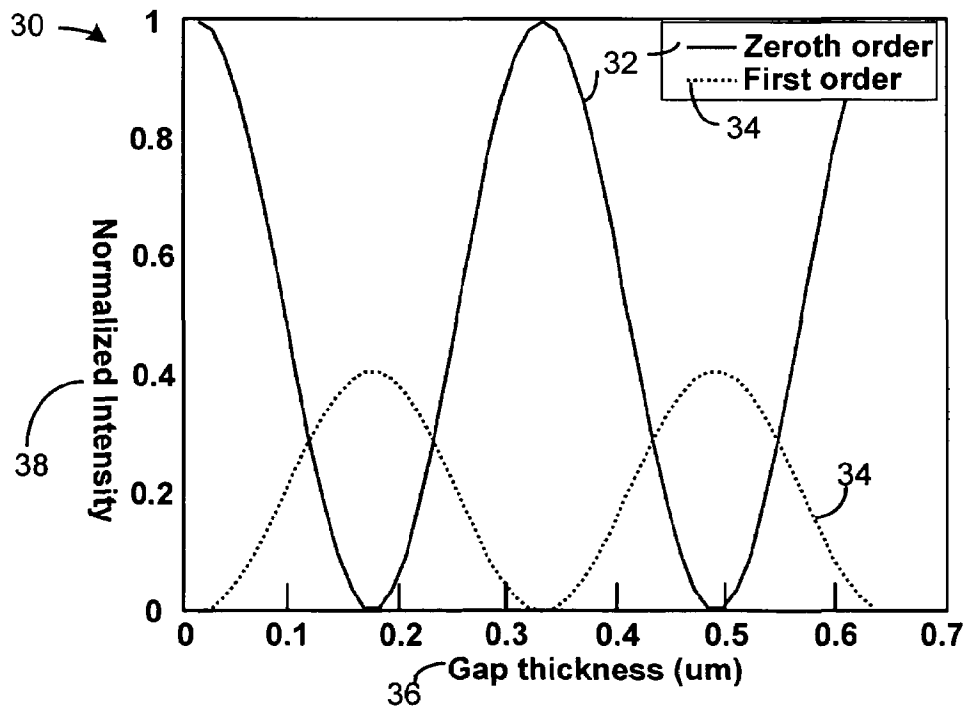


FIG. 1

**FIG. 2****FIG. 3**

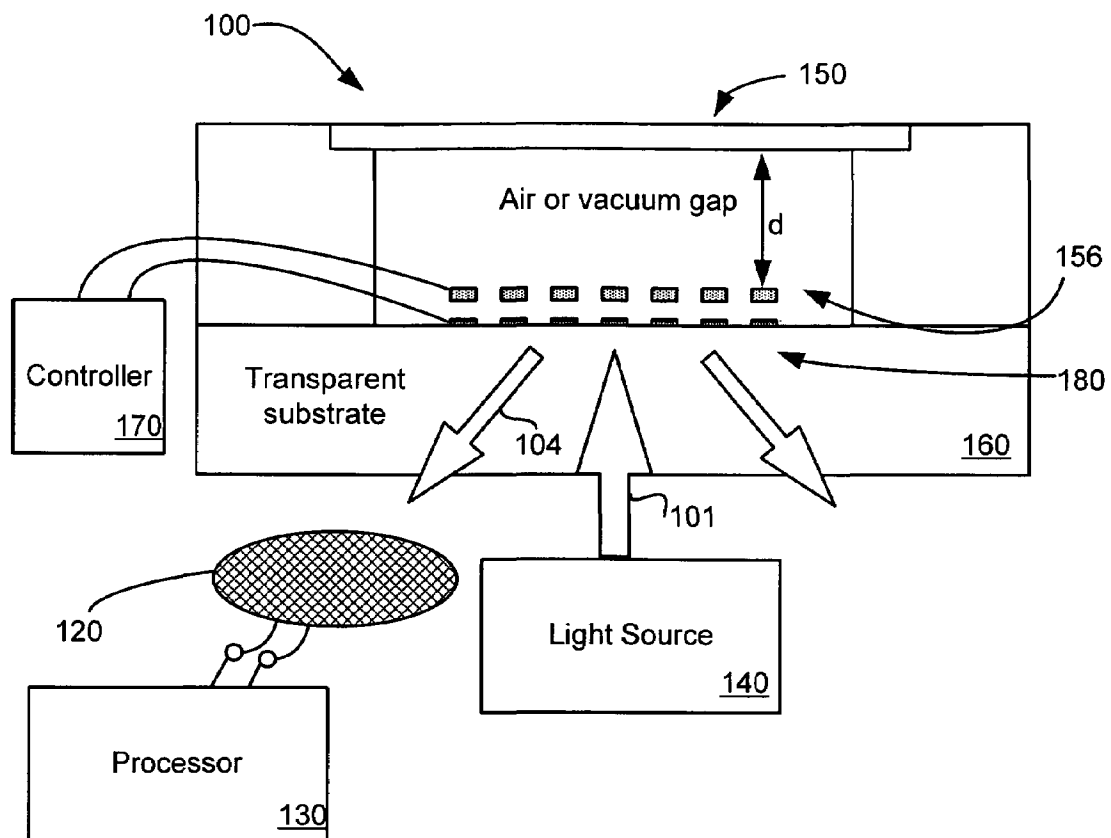


FIG. 4

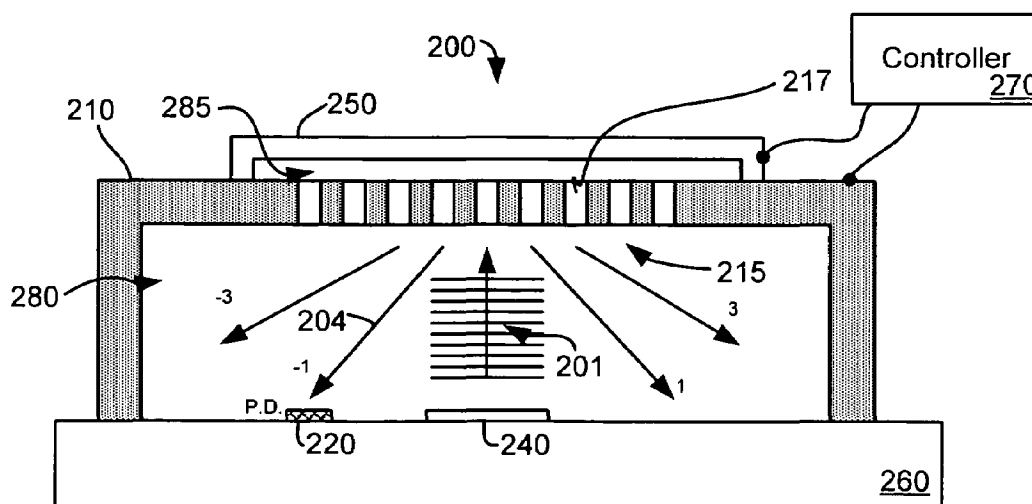
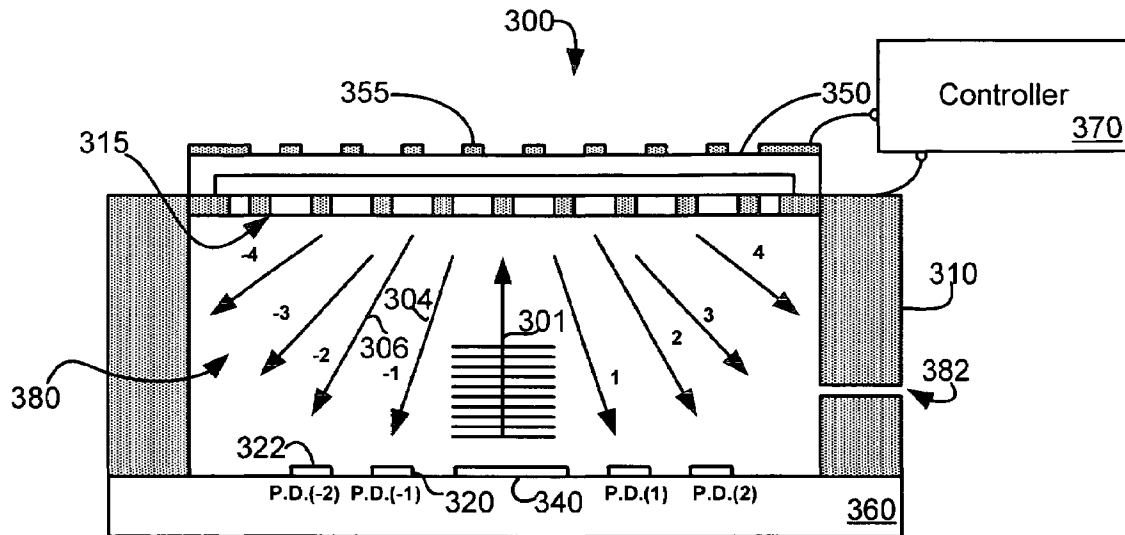
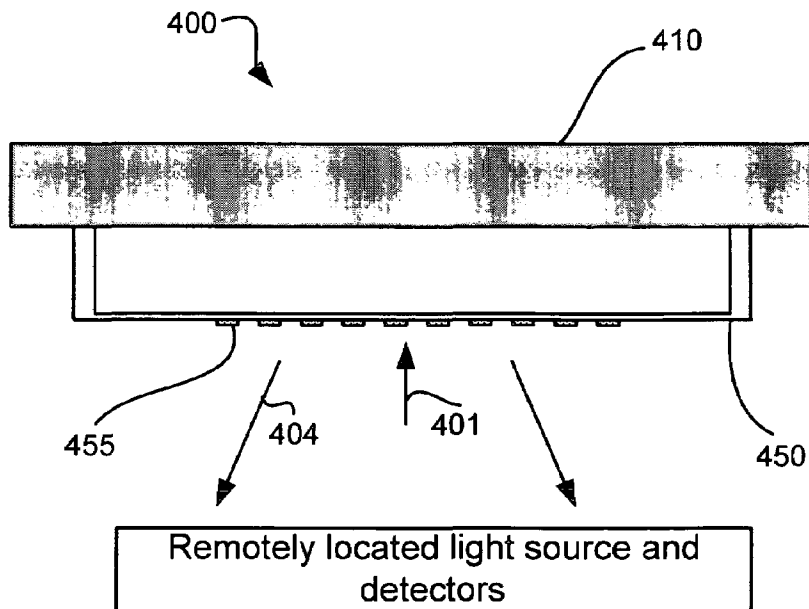
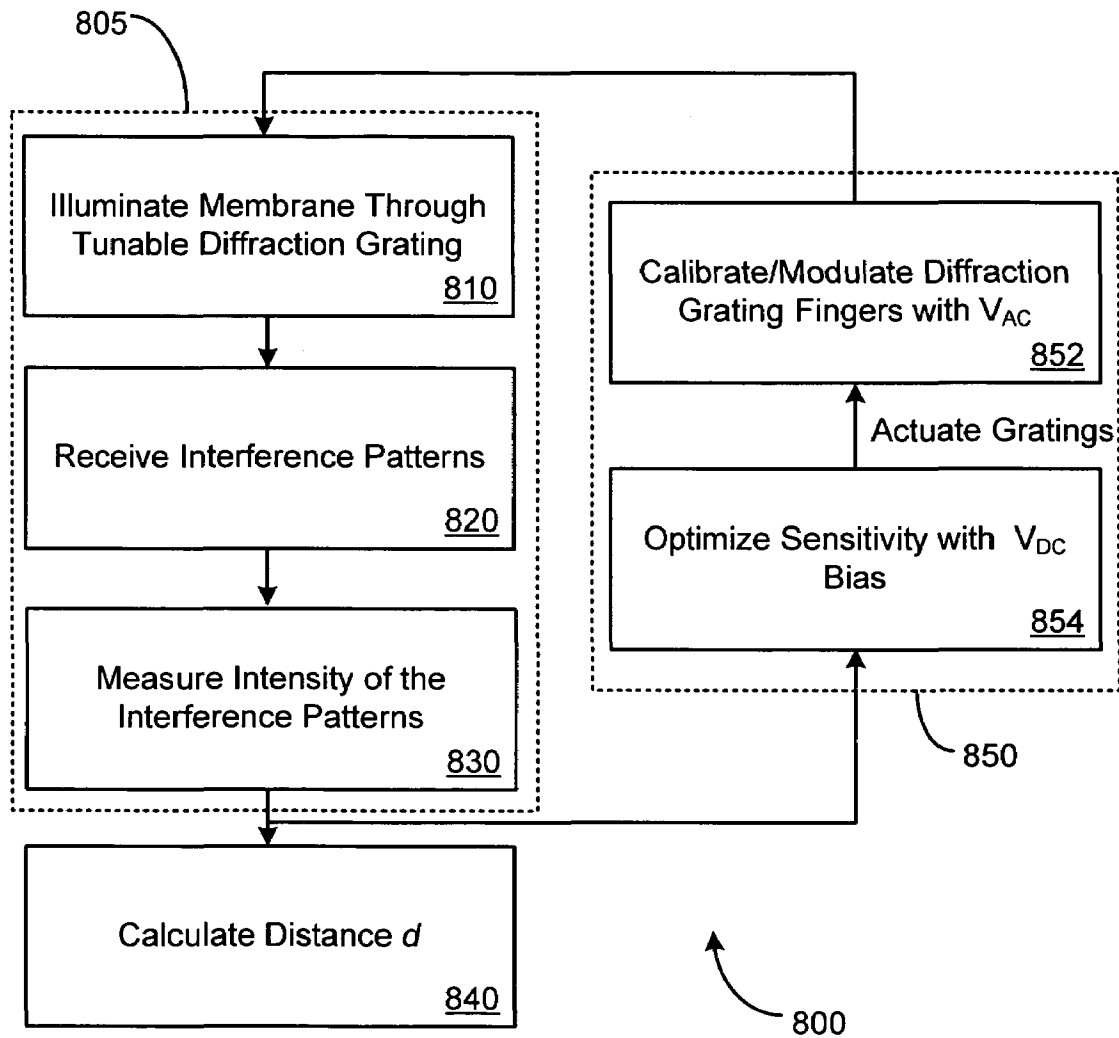


FIG. 5

**FIG. 6****FIG. 7**

**FIG. 8**

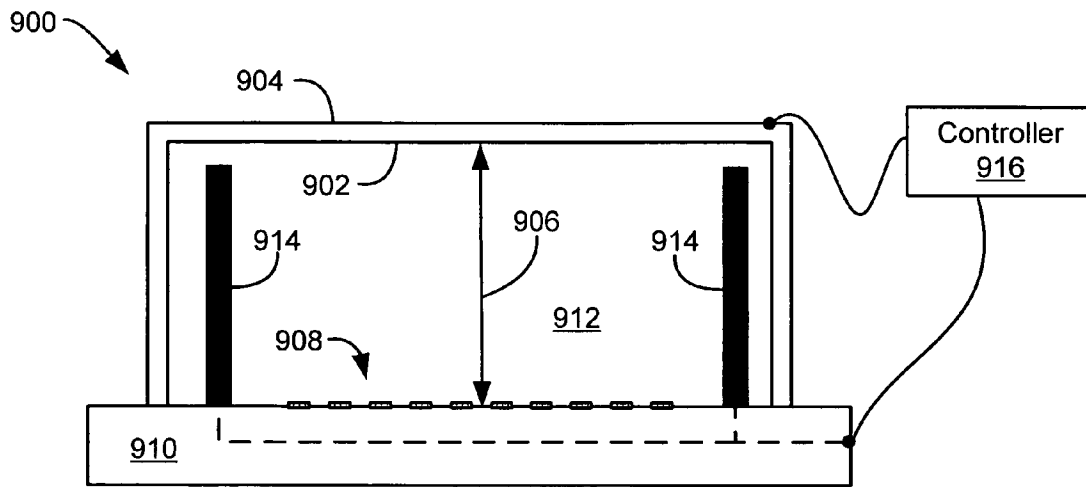


FIG. 9

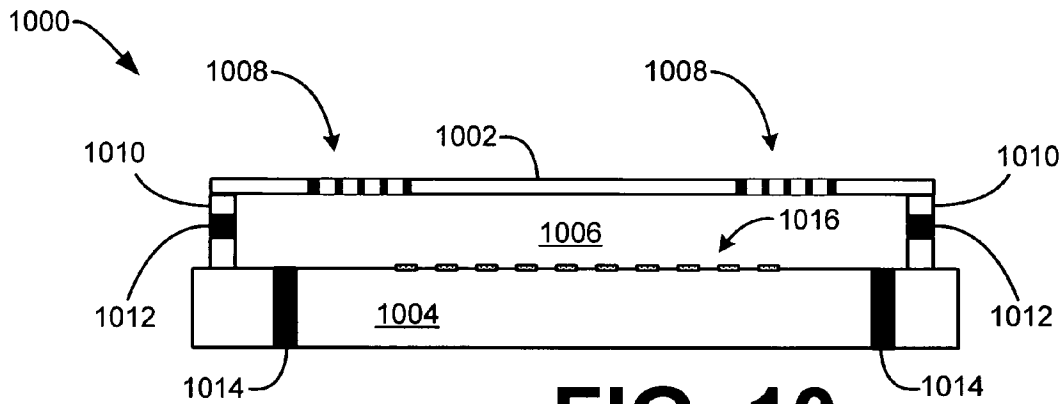


FIG. 10

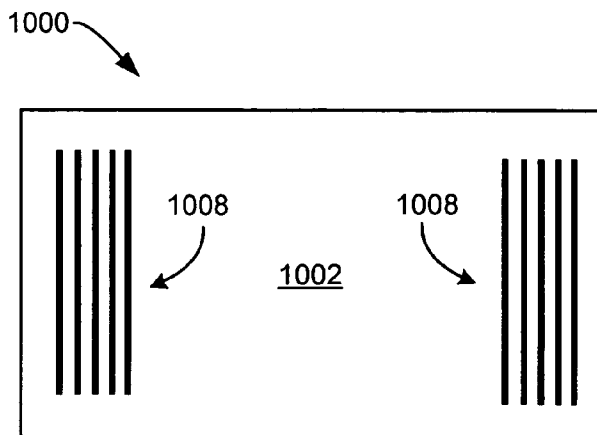


FIG. 11

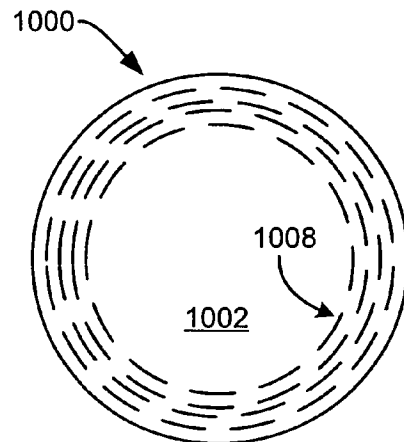


FIG. 12

HIGHLY-SENSITIVE DISPLACEMENT-MEASURING OPTICAL DEVICE

CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a Continuation-in-Part application of U.S. utility patent application "Highly-Sensitive Displacement-Measuring Optical Device," having Ser. No. 10/704,932, filed Nov. 10, 2003 now U.S. Pat. No. 7,116,430, which claims priority to U.S. provisional application "Miniature Diffraction-Based Optical Sensors," having Ser. No. 60/424,810 filed Nov. 8, 2002, and to which claims priority to, and is a Continuation-in-Part of, "Microinterferometers With Performance Optimization," having Ser. No. 10/112,490, filed Mar. 29, 2002 (now U.S. Pat. No. 6,753,969), each of which are incorporated by reference in their entirety.

This application is also related to U.S. utility patent application entitled "System and Method for Surface Profiling," having Ser. No. 10/113,362, filed Mar. 29, 2002.

This application is related to co-pending commonly assigned Non-Provisional Application entitled, "System and Method for Surface Profiling," filed concurrently herewith on Apr. 17, 2006, and accorded Ser. No. 11/405,053.

TECHNICAL FIELD

The present disclosure generally relates to measurement devices. More specifically, the disclosure relates to highly-sensitive, micron scale, displacement measurement devices.

DESCRIPTION OF THE RELATED ART

Hearing aids, for example, provide specific applications in which micron-scale displacement measurement devices may be used. Tiny microphone arrays are currently housed in hearing aids to pick up slight acoustic pressures. Today's microphones measure a change in capacitance between two conducting plates, one of which (the microphone diaphragm) moves as a function of the acoustic pressure applied.

There are various drawbacks to today's micromachined capacitive microphones. The electrical sensitivity of the microphone, S_e , is defined as the change in voltage output per change in membrane displacement. In a similar fashion, the mechanical sensitivity, S_m , is defined as the change in membrane displacement per change in applied pressure (i.e. S_m is simply the compliance or softness of the membrane). The total sensitivity of the device to sound pressure can then be expressed as $S_e \times S_m$, with units of Volts/Pa. For high S_e , a large DC bias voltage should be applied and the gap height between the electrodes should be made as small as possible, typically on the order of 2 μ m. These attributes are, in fact, in conflict, as the maximum DC bias that can be used is limited by the electrostatic collapse voltage, which decreases with shrinking gap height. The electrical sensitivity is a maximum when the device is biased near this electrostatic collapse voltage. Unfortunately, the detection scheme becomes non-linear under this same condition. In addition to this drawback, implementation of the constant charge condition can require the use of high impedance amplifiers, which come with high electronic noise. To compensate for poor S_e , micromachined capacitive microphones use large, soft membranes on the order of 1-5 mm to enhance mechanical sensitivity and, in turn, the overall device performance. Even this approach is limited, however, by membrane stresses that result during fabrication. These stresses bound the mechanical sensitivity

that can be achieved and make the fabrication of uniform membranes with high yield difficult. In addition to using a soft membrane, the back electrode can be perforated and open to a large backside cavity to prevent additional stiffening which would otherwise occur from compression of the air in the thin gap. The perforation reduces the active capacitance and adversely affects S_e , leading to yet another design conflict. In summary, the electrical and mechanical sensitivity in a micromachined capacitive microphone are not independent and impose severe design and fabrication limitations.

Optical interferometry is the act of splitting and recombining electromagnetic waves, in particular, visible light waves, to measure surface geometries, distance, etc. The advancement in interferometry has come in many avenues of technology. Long-range telescopes, high-precision spectrometers, compact disc players, etc., use some form of interferometry. Micro-machinery is a growing technology field that often utilizes interferometers because they typically have high resolution and precision. In general, displacement measurements in the sub-nanometer range can be detected with today's interferometers. To examine microscale structures, the lateral resolution of the interferometers, generally, need to be improved. This can be achieved by coupling the interferometer to a regular microscope. Unfortunately, the size of the interferometer becomes rather large and subsequently may not fit in small spaces for inspection. Furthermore, to inspect a large number of microscale structures either the sample or microscope objective is scanned, resulting in slow imaging.

In order to obtain interferometric measurement sensitivity in a small volume, several methods have been developed. One of these methods involves phase sensitive diffraction gratings as described in a technical paper entitled "Interdigital cantilevers for atomic force microscopy," published in *Appl. Phys. Lett.*, 69, pp. 3944-6, Dec. 16, 1996 by S. R. Manalis, S. C. Minne, A. Atalar, and C. F. Quate and also in U.S. Pat. No. 5,908,981 to Atalar et al.

Similar structures are also used in microaccelerometers to measure the displacement of a control mass with interferometric precision as described in a paper written by E. B. Cooper, E. R. Post, and S. Griffith and entitled "High-resolution micromachined interferometric accelerometer," *Appl. Phys. Lett.*, 76 (22), pp. 3316-3318, May 29, 2000. Both of these papers are incorporated by reference in their entireties.

Based on the foregoing, it would be desirable to incorporate optical interferometry with micro-machined microphone technology so as to improve over the current prior art. Furthermore, it would be desirable to explore other aspects in which highly-sensitive, micron-scale displacement measurement devices may be utilized.

SUMMARY

Micron-scale displacement measurement devices having enhanced performance characteristics are disclosed.

An embodiment of such a device includes a phase-sensitive reflective diffraction grating for reflecting a first portion of an incident light and transmitting a second portion of the incident light such that the second portion of the incident light is diffracted. The device further includes a mechanical structure having a first region and a second region, the mechanical structure positioned a distance d above the diffraction grating, the second portion of the incident light is reflected off of the first region of the structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light. The device further includes an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

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An embodiment of a method includes illuminating a reflective diffraction grating with an incident light, the diffraction grating being positioned a distance d from a mechanical structure having a first region and a second region, a first portion of the incident light being reflected and a second portion of the incident light transmitted through the diffraction grating such that the second portion of the incident light is diffracted. The method further includes reflecting the second portion of the incident light off of the first region of the mechanical structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light. The method further includes applying a voltage bias to an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

An embodiment of device includes means for illuminating a reflective diffraction grating with an incident light, the diffraction grating being positioned a distance d from a mechanical structure having a first region and a second region, a first portion of the incident light being reflected and a second portion of the incident light transmitted through the diffraction grating such that the second portion of the incident light is diffracted. The device can further include means for reflecting the second portion of the incident light off of the first region of the mechanical structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light. The device can also include means for applying a voltage bias to an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

Other devices, methods, features, and advantages of the present invention will be or become apparent to one with skill in the art upon examination of the following drawings and detailed description. It is intended that all such additional systems, methods, features, and advantages be included within this description, be within the scope of the present invention, and be protected by the accompanying claims.

BRIEF DESCRIPTION OF THE DRAWINGS

Many aspects of the disclosure can be better understood with reference to the following drawings. The components in the drawings are not necessarily to scale, emphasis instead being placed upon clearly illustrating the principles of the present invention. Moreover, in the drawings, like reference numerals designate corresponding parts throughout the several views.

FIG. 1 is a diagram illustrating the concept of using a diffraction grating to split beams in a microinterferometer.

FIG. 2 is a graph illustrating the distribution of reflected light measured on an observation plane with various gap thicknesses utilizing the method illustrated in FIG. 1.

FIG. 3 is a graph illustrating the normalized intensity of various diffraction orders vs. gap thickness utilizing the method illustrated in FIG. 1.

FIG. 4 is a diagram illustrating an embodiment of a micro-displacement measurement device in accordance with the present disclosure.

FIG. 5 is a diagram illustrating another embodiment of a micro-displacement measurement device in accordance with the present disclosure.

FIG. 6 is a diagram illustrating another embodiment of a micro-displacement measurement device in accordance with the present disclosure.

FIG. 7 is a diagram illustrating yet another embodiment of a micro-displacement measurement device in accordance with the present disclosure.

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FIG. 8 is a flow chart illustrating a method for optimizing the sensitivity of a micro-displacement measurement device and more generally improving the overall performance of a micro-displacement measurement device in accordance with embodiments of the present disclosure.

FIG. 9 is a diagram illustrating an embodiment of a micro-displacement measurement device in accordance with the present disclosure and having an increased air volume for improving the sensitivity of the device.

FIG. 10 is a diagram depicting a side, cut-away view of an embodiment of a micro-displacement measurement device in accordance with the present disclosure and having an open-gap structure for improving the sensitivity of the device.

FIG. 11 depicts a top view of an embodiment of a rectangular-shaped device having an open-gap structure of FIG. 10.

FIG. 12 depicts a top view of an embodiment of a circular-shaped device having the open-gap structure of FIG. 10.

DETAILED DESCRIPTION

As will be described in greater detail herein, displacement measurement devices in accordance with the present disclosure can measure the change in position of a membrane as a function of time due to a variety of factors. Furthermore, the displacement measurement devices can be optimized for displacement sensitivity and reduced noise causing a greater signal to noise ratio (SNR).

Referring now in more detail to the drawings, FIG. 1 is a diagram illustrating the concept of using a diffraction grating to split beams in a microinterferometer. This concept has been utilized in measuring precise relative displacements, such as for the measurement of Atomic Force Microscopy (AFM) tip displacement and in spatial light modulators, as in the grating light valves (GLV). This concept is also disclosed in U.S. Pat. No. 6,567,572 entitled "Optical Displacement Sensor" to F. L. Degertekin, G. G. Yaralioglu, and B. Khuri-Yakub, which is incorporated by reference in its entirety. AFM, in general, is a technique for analyzing the surface of a rigid material at the atomic level. AFM uses a mechanical probe to magnify surface features up to 100,000,000 times, and it can produce 3-D images of the surface. In general, a GLV contains several tiny reflective ribbons that are mounted over a silicon chip with a tiny air gap in between the chip and the ribbons. When a voltage is applied to the chip below a particular ribbon, that ribbon bends toward the chip by a fraction of a wavelength of an illuminating light. The deformed ribbons collectively form a diffraction grating and the various orders of the light can be combined to form the pixel of an image. The shape of the ribbons, and therefore the image information, can be changed in as little as 20 billionths of a second.

The diagram of FIG. 1 illustrates two scenarios. A first scenario 1 shows what occurs when a target surface 4 is placed a distance of a half-wavelength, $\lambda/2$, away from a reference point, in this case, a reflective diffraction grating 5. A second scenario 2 shows what occurs when the target surface 4 is placed a distance of a quarter-wavelength, $\lambda/4$, away from the diffraction grating 5. The detailed diffraction pattern of such a structure can be found by applying standard diffraction theory to determine the locations and the dimensions of the photo-detectors or light guide apertures.

In both instances, the reflective diffraction grating 5 is formed on a transparent substrate 3. Exemplary materials that may be utilized to construct such elements will be discussed in further detail in relation to FIG. 4. The diffraction grating 5 is formed of an array of diffraction grating fingers 6 equally spaced along a front edge of the transparent substrate 3. It should be noted that, as mentioned above, this diagram is not

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to scale, and is merely for illustrative purposes. In reality, the diffraction grating fingers 6 would typically have a height on the order of micro- or nano-meters.

In the first scenario 1, when an incident light is illuminated through the transparent substrate 3, a first portion of the incident light is reflected from the reflective diffraction grating 5. A second portion of the incident light is transmitted and diffracted about the diffraction grating fingers 6. The transmitted and diffracted light reflects off of the target surface 4 and is measured by a proper detection unit (not shown), such as a photo-detector or a photo-diode. As in scenario 1, the target surface is placed at a distance of $\lambda/2$ or any integer multiple, thereof. In this case, the 0th order of the transmitted incident light is reflected back. In general, the 0th order is the transmitted light that is illuminated directly, in which case no diffraction, or change in direction occurs. The first portion of the incident light, and the second portion of the incident light which has been reflected off of the target surface 4 interferes with each other. The phase of the two portions of the light waves help form constructive and destructive interference patterns. From the interference patterns, the relative distance between the diffraction grating 5 and the target surface 4 can be determined.

In scenario 2, the same general structure is set up. In this case, the target surface 4 is placed a distance of $\lambda/4$ away from the diffraction grating 5. In practice, the target surface 4 may be placed at any integer multiple of $\lambda/4$ and the same general results will occur. When the first portion of the incident light joins with the second portion of the incident light upon reflection, destructive interference cancels out the two. The second portion of the light travels an extra distance of $2\times$ the distance between the target surface 4 and the diffraction grating 3, which results in a phase difference between the two portions of π , complete destructive interference. On the contrary though, the higher order diffraction fields, such as the first order, can constructively interfere with the first portion of the incident light. As FIG. 1 depicts, the higher order first and second portions of the incident light are angled and not parallel to the line of illumination, like the 0th order beam.

Having described an example of using a diffraction grating to split light beams and therefore measure relative distance, theoretical calculations will be utilized to show the results of using the method described in FIG. 1. Suppose an incident light of $\lambda=632$ nm is illuminated through the transparent substrate 3 onto the reflective diffraction grating 5. A laser can be utilized to provide the incident light. In this case, a helium-neon (HeNe) laser can be utilized. Suppose the diffraction grating 5 contains 10 diffraction grating fingers 6 equally spaced at $d_g=2$ μm . FIG. 2 is a graph 10 illustrating the distribution of reflected light measured on an observation plane with various gap thicknesses utilizing the method illustrated in FIG. 1. Hereinafter, the distance between a reference point, in this case the diffraction grating 5, and the target surface 4 will be referred to as the gap thickness and can be considered the absolute distance to the surface.

FIG. 2 shows the normalized intensity of reflected light 20 versus an observation length, x 18. The observation length, x, is in the lateral direction, and centered at the 0th order beam. In this case, a 100 μm wide photo-detector has been used. Three scenarios are shown in the graph 10. Scenario 12 shows the normalized intensity 20 with gap thickness, $d=\lambda/2$. Scenario 14 shows the normalized intensity 20 with gap thickness, $d=\lambda/4$. Scenario 16 shows the normalized intensity 20 with gap thickness, $d=\lambda/8$.

As expected, scenario 12 shows the 0th order reflected beam with complete constructive interference. The higher order beams, e.g. the 1st and 3rd order beams, incur destructive

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interference and so their intensity is cancelled out. Scenario 14 shows that the 0th order has been completely cancelled out and the 1st and the 3rd orders of the reflected beam appear to have partial intensity. Scenario 16 shows that when the gap thickness, $d=\lambda/8$, both the 0th order and the 1st order contain some light intensity. Perhaps, most importantly, graph 10 attempts to show the periodic nature of the intensity of the orders of the reflected light versus varying gap thickness.

The intensity of these orders as a function of grating-reflecting surface shows the $\cos^2(2\pi d/\lambda)$ and $\sin^2(2\pi d/\lambda)$ variation, as illustrated in FIG. 3. FIG. 3 is a graph 30 illustrating the normalized intensity 38 of various diffraction orders 32 and 34 versus gap thickness 36 utilizing the method described in FIG. 1.

As shown in FIG. 3, the 0th order curve 32 takes on a $\cos^2(2\pi d/\lambda)$ shape. This is in line with the results found in FIG. 2. At gap thickness of $\lambda/2$, which is approximately 0.316 μm , the intensity is greatest. At gap thickness of $\lambda/4$, which is approximately 0.158 μm , the intensity is zero. The 1st order curve 34 takes on a $\sin^2(2\pi d/\lambda)$ shape. The graph 30 of FIG. 3 clearly displays the periodic nature of the diffraction orders. As one can see, keeping all other variables constant and known, one can calculate the relative distance by measuring the intensity of the orders, in particular the 1st order. In fact, by monitoring the intensity of any of the reflected orders, one can achieve interferometric resolution on the order of 1×10^{-5} $\text{\AA}/\sqrt{\text{Hz}}$.

The present disclosure provides a sensitive diffraction based optical displacement apparatus and method to measure the static and dynamic displacement of reflectors in various applications. The present disclosure includes the use of any type of reflector, however, in a preferred embodiment, the present disclosure includes a flexible and optically reflective membrane. The apparatus and method of the present disclosure is amenable to integration of electronics and optics to form compact displacement detectors for a single membrane or membranes fabricated in the form of arrays. Typical applications of the present disclosure would be in, for instance, but not limited to, microphones (micro-machined or not), micro-machined ultrasonic transducers, micro-machined ultrasonic wave generators, micro-machined ultrasonic image applications, pressure sensors and hearing aids. The embodiments of the present disclosure would also be useful in any sensing application where the position of a reflector or membrane is changed due to a chemical or physical process and this displacement needs to be measured accurately in a broad frequency range. Furthermore, the embodiments of the present disclosure would also be useful in any sensing application where the reflectivity of a reflector or a membrane is changed due to a chemical or physical process and this change needs to be measured accurately in a broad frequency range.

U.S. Pat. No. 6,567,572 entitled "Optical Displacement Sensor" discloses various embodiments of a micro-machined optical displacement sensor. For example, FIG. 4 of U.S. Pat. No. 6,567,572 illustrates an optical displacement sensor that includes a reflective diffraction grating 430 deposited upon a transparent substrate 420. Suspended above the diffraction grating 430 is a reflector 410. A voltage bias is applied across the reflector 410 and diffraction grating 430 so as to electrostatically actuate the reflector 410 to vary its position and/or rigidity.

An improvement to the sensor of U.S. Pat. No. 6,567,572 is embodied in the present disclosure. That is to add a semi-transparent layer to the top of the transparent substrate 420. This mirror layer can be built using a thin metal film and a dielectric stack of alternating quarter-wave thick media. Preliminary testing shows the thickness of the mirror layer and

the reflectivity of the metal used can greatly increase the sensitivity of the sensor. To complement the mirror layer placed on the transparent substrate **420** would be the reflective surface of the reflective membrane **410**. Similar testing of the thickness of the mirrored reflective layer of the membrane **410** and the material used proved complimentary results, however, keeping in mind that added thickness and the various materials used can affect the rigidity of the reflective membrane **410**.

FIG. **4** is a diagram illustrating a first embodiment of a micro-displacement measurement device **100** in accordance with embodiments of the present disclosure. As shown in FIG. **4**, the embodiments of the present disclosure provides for the use of a tunable, phase-sensitive diffraction grating **156** mounted above substrate **160** to measure the displacement of the membrane structure **150**. A light source **140** is integrated in the device **100** to provide an incident light beam to be shined on the reflective diffraction grating **156** and the reflective membrane **150**. A photo-detector **120** is positioned to receive the interference pattern produced by the reflected light beams. The embodiments of the present disclosure are not limited to the number of photo-detectors. In addition, the present disclosure includes another embodiment where the photo-detectors are one or more optical fibers. The main part of the device **100** consists of a flexible optically reflective membrane **150** suspended above a non-moving, transparent substrate **160**. For displacement detection, the intensity of the light **101** from light source **140** reflected from the membrane **150** and reflective diffraction grating **156** is monitored. Grating **156** consists of periodic reflective fingers positioned atop transparent, yet conductive, electrodes **180** which are deposited atop the transparent substrate **160**. Displacement of membrane **150** changes the intensity of the diffraction orders **104** which can be easily detected using standard photo-detector(s) **120**. This provides the sensitivity of an optical interferometer, and has a better noise performance as compared to other intensity based commercial optical microphones.

Light source **140** provides incident light beam **101** through substrate **160** to reflective membrane **150**. Reflective membrane **150** is positioned to diffraction grating **156** at an odd multiple of a quarter of the wavelength of light source **140**. In addition, the device **100** could include a wafer (not shown), preferably a silicon wafer for housing the light source **140** and/or the photo-detector **120**.

In order to realize a sensitive microphone one should have a compliant membrane, which can be displaced by pressure fields and a detection scheme to detect membrane displacements at the pressure levels in the order of 105 Pa. The pressure equivalent of the thermal mechanical noise of the membrane structure should be small since this number determines the minimum detectable pressure level. It is preferable that a broadband microphone have a membrane response free of resonances in the bandwidth of interest and a broadband detection scheme. The micro-machined microphone membrane and the integrated optical detection scheme satisfy these preferred attributes. The device can also transmit sound and can be self-calibrating by the application of bias voltages between the electrodes **180** and grating **156**. In the following description, the elements and operation of the microphone are discussed in detail.

The light source **140**, in this embodiment, may be a laser, that emits an electromagnetic wave at a known wavelength, λ . An emitted incident light beam **101** would be illuminated onto the reflective diffraction grating **156**. In this embodiment, a Helium-Neon (HeNe) laser ($\lambda=632$ nm) may be utilized. In other embodiments, the light source **140** may be a laser emitting another known wavelength. The exact wave-

length of the incident light beam **101** may vary as long as the dimensions of the components of the device **100** are calculated in terms of the incident light beam **101** wavelength. To that, light sources emitting more than one known wavelength can be utilized as well, although, preferably, a light source emitting one known wavelength would be utilized. In practice, any kind of temporarily coherent light source with a coherence length equal to or greater than two times the distance between the membrane **150** and the diffraction grating **156** may be utilized. The light source **140** may also be a Vertical Cavity Surface Emitting Laser (VCSEL) mounted on a wafer or printed circuit board.

In other embodiments, the incident light beam **101** may be carried via an optical fiber, in which case the light source **140** may be located remotely. As depicted in FIG. **4**, the light source is positioned normal to the plane of the transparent substrate **160**. Utilizing an optical fiber adds flexibility in placing the light source **140**.

In yet other embodiments, the incident light beam **101** may be guided towards the diffraction grating **156** via a wave guide and/or a set of properly placed mirrors. For instance, the light source **140** may be placed relatively parallel to the lengthwise direction of the transparent substrate **152**. In this case, a mirror and/or a wave guide can change the direction of the incident light beam **101** so that it is illuminated at a direction normal to the diffraction grating **156**. To that, although it appears that the best results occur when the incident light beam **101** is illuminated at a direction normal to the diffraction grating **156**, it need not be necessary. Other wave shaping instruments may be utilized, such as microlens, to collimate the incident light beam **101**. The reflected light beams **104** may also be shaped by a system of wave shaping instruments.

The transparent substrate **160** is typically a planar surface, although not necessarily. For example, the substrate **160** may be cut so as to have a rounded surface for the forming the diffraction grating **156**. This may aid in focusing the incident light beam **101**. A variety of materials can be utilized for the substrate **160**. Non-limiting examples are quartz, silicon, sapphire, glass, and combinations thereof. In other embodiments, the substrate **160** may be non-transparent, but a bulk-etched cavity may be incorporated into the substrate **160** to allow illumination. In general, the transmission coefficient, τ , of the transparent substrate **160** for a given wavelength of incident light beam **101** may be larger than 0.9. The dimensions of the transparent substrate **160** can vary according to the overall structure of the device **100**, but in general, the lateral thickness of the substrate **160** may be in the range of 0.1 mm-2 mm, and likewise having a working distance of 0.1 mm-2 mm with an F-number from 1 to 5. The lateral length can vary with the structure of the device **100**. In other embodiments, the transparent substrate **160** may be configured, upon manufacture, to assist in focusing the diffracted and/or collimated incident light beams.

In an alternative embodiment, the displacement sensitivity can be improved by fabricating a semi-transparent mirror layer on the top surface of the transparent substrate **160**.

As mentioned, the diffraction grating **156** may include several equally spaced fingers. In general, the spatial separation between adjacent fingers may be on the order of the wavelength of the incident light beam **101**. The fingers may be constructed of a reflective and conductive material that has a reflection coefficient of between 0.8 to 1. The conductivity of the diffraction grating fingers may be necessary for electrostatic actuation of the fingers. In general, the fingers may be shaped as blocks and could also be composed of a conductive material with a non-dielectric reflective coating. In other

embodiments, the fingers may be composed of a dielectric material and be coated with a conductive reflective material. The dimensions of the fingers can vary greatly with the wavelength of the incident light beam **101**. In this embodiment, however, the dimensions of the fingers may be on the order of the wavelength of the incident light beam **101**, or about 0.5 μm to 10 μm . Several fingers (on the order of 10λ in lateral length) may make up the diffraction grating **156**. In this embodiment, the diffraction grating **156** is formed above the top planar surface of the transparent substrate **160**.

The diffraction grating fingers need not be equally spaced. The diffraction grating **156** may be configured to focus the incident light beam **101** to a given focal point. This may be accomplished by varying the spacing between the fingers in such a way so as to focus the light.

The electrodes **180** are placed in relation to the diffraction grating fingers. In general, the electrodes **180** are a conductive material that is deposited onto the substrate **160**. Similar to the diffraction grating fingers, the electrodes **180** may be a dielectric material covered with a conductive coating. The electrodes **180** may also be made of a transparent material coated or doped with a conductive material.

The device **100** also includes a photo-detector **120**. In this embodiment, the photo-detector **120** may be placed parallel and underneath the substrate **160**. As the figure depicts, the photo-detector **120** may be positioned to receive a higher diffraction order of the reflected light, such as the 1st or 3rd order. The observation length, x , can vary, but should be properly positioned so that a higher diffraction order may be observed. For example, the observation length x , may vary with the wavelength of the incident light beam **101**. The photo-detector **120** may be placed at an optimal longitudinal distance, e.g. 1000 μm , but this may vary with wavelength.

In other embodiments, the photo-detector **120** may be remotely located and the diffracted light may be received via an appropriately placed optical fiber. In yet other embodiments, a wave guide and/or mirrors may change the direction of the diffracted and reflected beams. In this embodiment, as mentioned, the photo-detector **120** is placed parallel to the substrate **160**. This allows for a relatively small space, on the order of 100 μm -1000 μm .

Several photo-detectors **120** are known in the art. In general, any photo-detector **120** that can be configured for micro-machining and can sustain the desired bandwidth can be utilized. One specific example of a photo-detector **120** that can be used is a silicon P-N junction photodiode. Another type that could be utilized is a P-I-N type photodiode. The utilized photo-detector **120** may depend on the processing speed and responsivity (photocurrent per Watt of incident light) requirements. For example, at wavelengths where the absorption of silicon is small, deeper junction depths may be used to increase responsivity.

Similarly, the geometry of the photo-detector **120** may be adjusted to minimize its capacitance and transit time to increase the detection bandwidth. Some signal conditioning circuitry, such as a transimpedance amplifier, may also be implemented on the same semiconductor substrate as the photo-detector **120** to minimize noise and decrease parasitic capacitance. These photo-detectors **120** with integrated electronics can be configured to operate with bandwidths from DC to GHz range for sensing optical communication applications.

A processor **130** may be included within the device **100**, but more than likely will be communicatively coupled to the photo-detector **120** and be an external component. The processor **130** may be any type of electrical component that can process the signals received by the photo-detector **120**. Like-

wise, hardware, software, and/or firmware may be utilized to properly make the appropriate calculations. For example, a personal computer may be configured to process the signals received from the photo-detector **120** in data that is compiled and calculated to produce the change in distance d as a function of time. A relatively simple digital signal processor (DSP) or an application specific integrated circuit (ASIC) may be utilized to perform the calculations. The processor **130** may also be capable of making several other calculations and/or perform other functions, such as calibration, laser intensity normalization, digital filtering, and signal conditioning.

Coupled to the diffraction grating **156** and electrodes **180** is a controller **170** for controllably adjusting, in this embodiment, the position of the diffraction grating. This is accomplished by electrostatic actuation which is discussed below. The controller **170** may be communicatively coupled to the processor **130**. In this manner, force-feedback approaches to measuring the distance d can be accomplished.

The structure of the devices of the present disclosure include a phase sensitive optical diffraction grating, in which the diffraction pattern is determined by the membrane **150** displacement relative to the diffraction grating **156** (which position can vary, to be discussed below). The incident light will be reflected back to the zeroth order when the gap thickness is an integer multiple of $\lambda/2$, and to the odd diffraction orders when the gap thickness is an odd multiple of $\lambda/4$. Notably, as illustrated in FIG. 3, the change in intensity of both orders per gap thickness is maximized in a periodic fashion in these multiples. Operating the device **100** at the point of maximum change in intensity (the slope of the cos and sin curves of FIG. 3) is beneficial because it maximizes the sensitivity of the device **100**.

As illustrated in FIG. 4, the photo-detector **120** is positioned to receive the first order, which has maximum change in intensity at odd multiples of $\lambda/4$. Notably, when a single photo-detector is used to detect the intensity of a diffraction order the output signal will include the effect of laser intensity noise degrading the performance of the device **100**. This noise can be eliminated by normalizing the output signal with the laser output power. By way of using arrays of these devices **100** to form a microphone, the noise level will be further reduced by spatial averaging.

In order to operate the device **100** at the maximum sensitivity and to adjust for the ambient pressure changes, there can be a DC bias voltage applied between electrodes **180** and grating **156**. Adding an AC signal to the bias, the device **100** can be used as a regular cMUT, which can transmit sound as well as receive acoustic signals. The DC and AC voltages electrostatically actuate the grating fingers causing them to bend (when voltage is applied) toward the electrodes **180**, thus causing a change in the distance from grating **156** to reflective membrane **150**. This change in distance causes a change in the interference pattern produced, which can be advantageous if the electrostatic actuation is performed in a controlled manner. The controller **170** can be configured to apply the electrical signals to perform the electrostatic actuation. The controller **170** may be coupled to the processor **130** to form a feedback loop. In this manner, the position of the grating **156** can be varied such that the device **100** is calibrated to measure at optimal sensitivity. Furthermore, by utilizing a modulation signal which can be applied to the electrodes **180** and grating **156**, and utilizing commonly known frequency lock-in methods noise can be filtered out, thus increasing the SNR of the device **100**.

FIG. 5 is a diagram illustrating another embodiment of a micro-displacement measurement device **200** in accordance

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with embodiments of the present disclosure. The device includes a light source **240** and a photo-diode **220** on the surface of an opaque, rigid substrate **260**. An optical diffraction grating **215** exists above the light source **240** and is characterized by alternating regions of reflective and transparent passages **217**. A backside cavity **280** formed between the grating **215** and the substrate **260** may be sealed at some desired pressure (including low pressures) with any gas or gas mixture, or can be open to ambient through an opening with desired flow resistance. Finally a reflective membrane **250** exists above the diffraction grating **215** that reflects light back towards the substrate **260**. The diffraction grating **215** and the reflective membrane **250** together form a phase-sensitive diffraction grating.

The diffraction grating **215** is formed on a silicon substrate by first depositing an oxide layer followed by the deposition and patterning of a conductive and reflective thin film such as polysilicon in the form of a grating. A silicon nitride layer deposition is used to encapsulate the grating fingers and then patterned to expose the underlying oxide between the grating fingers. The grating is released by first etching the bulk silicon using a deep reactive ion etching which stops at the oxide layer. This is followed by wet etching of the oxide between the grating fingers hence providing free space optical access to the reflective top membrane.

The reflective membrane **250** is suspended in a bridge-like structure and may be composed of a non-conductive material, such as a stretched polymer membrane, polysilicon, silicon-nitride, or silicon-carbide, and then making the material conductive in a desired region either through depositing and patterning a conductive material such as aluminum, silver, or any metal. Alternatively, the non-conductive material may be doped with a conductive material. The reflective membrane **250** can also be coated with a reflective material, which makes aluminum or silver a good choice. In some applications such as chemical and biological sensors, the reflective membrane **250** can be made of a single material or a multi-layered material that change its optical properties, such as reflectivity in response to a chemical or biological agent for example a polymer film dissolving in a solvent. Similarly, the reflective membrane **250** can be a micromachined cantilever made of single or layered material that deforms, or moves, due to thermal, chemical, or other physical stimulus. For example, the device **200** can be configured to be an infrared (IR) sensor by having a bimorph structure as the reflective membrane **250** that includes an IR absorbing outer layer and a reflective layer facing the light source **240**. In some other applications, such as a microphone or a pressure sensor, the reflective membrane **250** can be in the shape of a diaphragm.

A gap **285** is formed between the rigid structure **210** and the reflective membrane **250**. The gap **285** should be large enough to have at least one optimal detection sensitivity point, i.e., highest slope of the curves **32**, **34** and smaller than half the coherence length of the light source. The backside cavity **280** is used to adjust the effect of air on the mechanical response of the membrane **250**. If the cavity **280** is very small, the spring-like stiffness of the air will be high as compared to the membrane stiffness and hence dominate the overall mechanical response. Utilizing a large cavity, e.g. $500 \times 500 \times 500 \mu\text{m}^3$, the air stiffness can be reduced to negligible levels. Another function of the backside cavity **280** is to provide optical access and longitudinal distance for the separation of diffraction orders for detection by photo-detectors **220**.

A controller **270** may be coupled to the reflective membrane **250** and the rigid structure **210** so as to apply a voltage bias to electrostatically actuate the reflective membrane **250**. When a controlled voltage bias is applied, various aspects of

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the reflective membrane **250** can be altered. First, the position, with respect to the diffraction grating **215** can be changed. Secondly the rigidity of the reflective membrane **250** may be altered. In many applications, moving or controlling the position of the reflective membrane **250** will be desired for self-calibration, sensitivity optimization, and signal modulation purposes. For example, if the reflective membrane **250** is a diaphragm as in the case of a microphone or a capacitive micromachined transducer, vibrating the diaphragm to produce sound in a surrounding fluid may be desired for transmission and self-calibration. Also, while measuring the displacement of the diaphragm, controlling the nominal gap height to a position that will result in maximum possible sensitivity for the measurement may be desired.

The substrate **260** may be a printed circuit board, a silicon wafer, or any other solid material. Furthermore, the light source **240** and photo-diode **220** may be constructed or sourced externally and attached to the surface or fabricated directly into the material using integrated circuit or micromachining fabrication techniques.

The light source **240** can be an optical fiber or end of a microfabricated waveguide with an appropriate reflector to direct the light to the desired location in the device **200**. The light source **140** of the embodiment illustrated in FIG. **4** is similar to the light source **240** here. Likewise, the photo-diode **220** serves as a specific example of a photo-detector, as discussed in relation to FIG. **4**.

The operation of the device **200** is fairly similar to that of device **100**. An incident light beam **201** is illuminated upon the diffraction grating **215**, where in turn a first portion of the light is reflected back towards the substrate **260**. A second portion of the light is diffracted about the diffraction grating **215** and reflected off of the reflective membrane **250** back toward the substrate **260**. An interference pattern of the two reflective portions is formed. A photo-diode **220** is positioned to receive, in this embodiment, the first order of the interference pattern. Various functions can alter the reflective membrane **250**, thus changing the interference pattern. First, the distance of the reflective membrane **250** relative to the diffraction grating **215** (the gap **285** height) can change due to a number of reasons. One reason is due to a number of external excitations, such as acoustic pressure causing the membrane **250** to vibrate at a particular frequency. Another external excitation may be because of a chemical reaction occurring on the membrane **250**, such as change in the residual stress in a composite membrane due to dissolution of one of the layers. A third external excitation may be an infrared light source illuminated upon the membrane **250**, causing the membrane **250** to change position. There are a great number of possibilities that can alter the position of the reflective membrane **250**, all of which are too many to list here. The controller **270** can also be factored into the movement of the reflective membrane **250** either in a modulated approach or a static approach.

Second, the reflectivity of the membrane **250** may be altered, such that the power level of the second portion of the reflected light is altered. This change in the power level can be detected by the photo-diode **220**. The reflectivity of the membrane **250** may be altered by a chemical or biological reaction. Examples of these reactions can be those causing a color change or change in membrane thickness. It is well known that the reflectivity of thin films strongly depends on thickness. Therefore corrosion, etching, or deposition of different materials on the membrane **250** due to chemical or biological processes will alter the reflected light.

Third, the rigidity of the membrane **250**, and thus the magnitude in which the membrane **250** will vibrate can be altered in time and measured by the photo-diode **220**. The

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rigidity of the membrane **250** may be a factor of an external force, but more than likely will be caused by an electrostatic charge applied by the controller **270**. Varying the rigidity of the membrane **250** provides for another possibility. That is to vary the rigidity of the membrane **250** as a function of the acoustic pressure applied to the membrane **250**. The attempt would be to keep the membrane **250** as still as possible. With this approach, one can measure the varying voltage needed to accomplish this, and thus be using a force-feedback approach to measure the applied acoustic pressure. Force-feedback is a well known method in the art that can typically produce more accurate and sensitive results. The device **200** can be made at such a small scale, that it is very practical to string together these devices in an array or matrix structure. Being able to build microphone arrays on a single substrate over a small surface area allows fabrication of devices with closely matched responses. By measuring the acoustic pressure using several closely spaced, matched microphone array elements the pressure gradients may be measured accurately to implement acoustic intensity probes. Furthermore, some signal processing methods such as gradient flow algorithms results in significant noise reduction using a two-dimensional array of microphone arrays with a periodicity much smaller than the acoustic wavelength. The embodiments of the present disclosure enable implementation of such closely spaced microphones without loss of signal fidelity.

FIG. **6** illustrates some variations to the embodiment illustrated in FIG. **5**. First, an air release channel **382** could be implemented in either of the devices **200** or **300**. The air release channel **382** serves to equalize the pressure inside the cavity **380** with the ambient pressure preventing the collapse of the microphone membrane **350** in response to changing ambient pressure which can be due to wind or other non-acoustic changes in atmospheric pressure.

Secondly, a second diffraction grating **355** can be deposited on a transparent membrane **350** rather than a membrane with a mirror-like uniform reflective surface as in the previous embodiments. The grating **355** on the membrane **350** has the same periodicity as the first, the reference, diffraction grating **315**, but is offset and has diffraction grating fingers whose width is smaller than the gap between the fingers of the reference diffraction grating **315**. This structure allows some of the incident light to transmit through the whole device **300** and also introduces new diffraction orders in the reflected field. This produces a new kind of phase grating.

To understand the operation one can consider the phase of the light reflected from the reference grating (ϕ_1) and the grating on the membrane (ϕ_2). When the difference between ϕ_1 and ϕ_2 is $2k\pi$, $k=0, 2, 4, \dots$, the apparent period of the grating is Λ_g (apparent reflectivity of 1, 0, 1, 0 regions assuming perfect transmission through the transparent membrane **350**) and the even diffraction orders are reflected with angles

$$\sin(\theta_n) = n \frac{\lambda}{\Lambda_g}, n = 0, \pm 2, \pm 4 \dots$$

In contrast, when the difference between ϕ_1 and ϕ_2 is $m\pi$, $m=1, 3, 5, \dots$, the apparent period of the grating is $2\Lambda_g$ (apparent reflectivity of 1, 0, -1, 0, 1 regions assuming perfect transmission through the transparent membrane **350**) and the odd diffraction orders are reflected with angles

$$\sin(\theta_n) = n \frac{\lambda}{2\Lambda_g}, n = 1, \pm 3, \pm 5 \dots$$

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Here it is assumed that the width of the reflective grating fingers on the reference grating **315** and the grating **355** on the membrane **350** are the same. This does not have to be the case if the interfering beams go through different paths and experience losses due to reflection at various interfaces and also incidence angle variations. The diffraction grating geometry can then be adjusted to equalize the reflected order intensities with optimized interference.

Note that in this embodiment, the intensity of the odd and even numbered orders change with 180° out of phase with each other when the gap between the reference and sensing diffraction grating changes. The even numbered diffraction orders are in phase with the zero order reflection. The advantage of having other off-axis even diffraction orders in phase with the specular reflection is that it enables one to easily use differential techniques. This is achieved by taking the difference of the outputs of two detectors (i.e., photo-diodes **320** and **322**) to detect odd and even orders, respectively. Hence, the common part of the laser intensity noise which is common on both orders can be eliminated.

Similar electrostatic actuation techniques can be applied by the controller **370**. Furthermore, similar to the device **200** of FIG. **5**, the device **300** can be fabricated at such a small scale that it is very feasible to arrange many devices **300** in an array or matrix structure.

FIG. **7** illustrates yet another embodiment of the present disclosure. In this embodiment, a reflective diffracting grating **455** is located on a transparent membrane **450**. A platform **410** includes a reflective surface, and the device **400** forms a phase sensitive diffraction grating when illuminated from the bottomside of the membrane **450** with an incident light beam **401**. The zero and all odd orders are reflected back and have intensities that depend on the distance between the grating **455** and the platform **410**. Note that this gap includes the thickness of the membrane **450**, which may be made of any transparent material. Examples include silicon dioxide, silicon nitride, quartz, sapphire, or a stretched polymer membrane such as parylene.

Since the only potential requirement of the platform **410** is to be reflective, any material including semiconductor substrates or plastics can suffice given that they are coated with a reflective layer, such as metal. To add the electrostatic actuation feature, a region of both the platform **410** and the membrane **450** can be made electrically conductive. For the membrane **450**, this can be accomplished by using a material that is both reflective and conductive for the diffraction grating **455**.

This particular embodiment offers remote sensing capabilities, as the light source, as well as any photo-detectors, may be located remote from the device **400**. For example, if measuring the displacement of the membrane **450** due to a change in pressure is desired (as would be the case for a pressure sensor or a microphone), the platform **410** can be attached to a surface and the light source and detectors can be stationed in a remote location not necessarily close to the membrane **450**.

In addition to remote measurements, this device **400** can be remotely actuated to modulate the output signal. For example, an acoustic signal at a desired frequency can be directed to the membrane **450** and the output signal can be measured at the same frequency using a method such as a lock-in amplifier. The magnitude and phase of the output signal would give information on the location of the membrane **450** on the optical intensity curve of FIG. **3**, which in turn may depend on static pressure, and other parameters such as temperature, etc. Similar modulation techniques can be implemented using electromagnetic radiation, where an electrostatically biased

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membrane **450** with fixed charges on it can be moved by applying electromagnetic forces. In this case, the membrane **450** would be made with a dielectric material with low charge leakage.

FIG. **8** is a flow chart illustrating a method **800** for optimizing the sensitivity of a micro-displacement measurement device and more generally improving the overall performance of a device in accordance with embodiments of the present disclosure.

The method **800** begins with measuring the distance d (block **805**). Once the distance is measured by the device, the measurement data can be processed so that the distance can be calculated (block **840**). Typically, this can be performed by a processor, which may be a computing device such as a personal computer. The processor may be configured to perform several other functions with the data as well.

Either before or after the data is calculated, a control signal may be generated based on the measured and/or calculated data to actuate fingers of a tunable diffraction grating of the device (block **850**) or actuate the reflective membrane. Once the device has been appropriately actuated, the measurements may be made again. This procedure may continue, as the feedback loop provides for constant monitoring.

As described in sufficient detail in prior figures, several embodiments of devices can properly measure the distance d , and the change of d in time. A simplified description of the general method of measuring the distance may begin with illuminating the reflective membrane with an incident light beam through the tunable diffraction grating (block **810**). Once illuminated, interference patterns can develop through constructive and destructive interference of reflected light off of the tunable diffraction grating and reflections off of the membrane that has been diffracted through the diffraction grating. A photo-detector may then receive the interference pattern (block **820**). Once received proper electrical components working with the photo-detector or included within the photo-detector may then measure the intensity of light of the interference patterns (block **830**). Interpretation of the interference patterns may come in subsequent calculations.

From either the measured intensity of the interference patterns or from processed calculations, a voltage potential may be generated that carries proper actuation information. The voltage potential may carry a DC portion that can deform chosen fingers of the tunable diffraction grating to certain predetermined optimum positions. Alternatively, the reflective membrane may be actuated and moved to a position that produces optimum sensitivity (block **854**). Upon actuation, an AC portion of the voltage potential may also be supplied that can act as a calibration signal during sensitivity optimization. For example, the DC bias can be changed until the diffracted light intensity variation at the AC signal frequency is maximized for a certain AC displacement. The AC signal can also act as a modulation signal to vary the distance d at a known frequency (block **852**). As a result, upon calculation, known frequency lock-in detection techniques can be used to lock in at the modulating frequency. Any vibrations from noise can thus be overcome, because, in essence they are modulated out. Improving the sensitivity of the device and eliminating noise in the system can help optimized the performance of the device.

According to some embodiments of the disclosed devices, the sensor structure can be modified to enhance desired performance characteristics. For example, the mechanical sensitivity for the disclosed sensor structures can be defined as the maximum displacement of the membrane for a given pressure. The membranes described thus far have generally been described as being uniform in thickness, and the mem-

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branes deflect into a concave shape when a net pressure is applied on the top side of the membrane. Thus, such maximum displacement can be measured, for example, from the center of the concave membrane displacement. Since the membrane displacement is detected optically for such devices, it can be desirable to have as flat of a deflection profile as possible, while still maintaining good mechanical sensitivity. Said another way, it can be desirable for the reflective surface of the membrane to be flat, even during the deflection of the membrane.

According to one embodiment, a sensitivity increase can be achieved using an increased gap thickness to provide an air-sealed cavity having a volume larger than devices having relatively smaller gap thicknesses. For example, with reference to FIG. **9**, a sensor **900** is disclosed having such an increased gap height to reduce the stiffness of trapped air within the cavity, thereby increasing the mechanical sensitivity of the membrane.

More specifically, FIG. **9** illustrates a device having similar operating principles of the sensor structures of the previously described microphones. Similar to the devices of FIGS. **1** and **2**, for example, device **900** includes a target surface **902** (which may be a reflective surface of a mechanical structure **904**, such as a beam or flexible membrane) placed a distance **906** away from a reference point. In this case, the reference point is a reflective diffraction grating **908** formed on transparent substrate **910**.

When air is trapped in the membrane-substrate gap a substantially air-tight sealed cavity **912** is formed. However, a reduction in mechanical sensitivity may occur due to the added stiffness caused by the compression (or vacuum) of trapped air when the membrane is deflected. Therefore, additional enhancements in mechanical sensitivity can be made by reducing this effect.

The stiffness due to the air is inversely proportional to the volume of the cavity **912**. Thus, the stiffness can be reduced by increasing the gap height appropriately (i.e. distance **906**). The sensitivity of the optical detection method is not adversely affected by large gap heights, so long as the coherence length requirement of the light source is met. Thus, distance **906** can be a relatively large distance in comparison to the gap thicknesses described in other embodiments such that the volume of air in cavity **912** is increased to effectively increase the sensitivity of the device.

However, the disclosed device embodiments that are configured to electrostatically actuate the membrane may not operate as effectively with a larger gap height. That is, the electrostatic actuation force used to move the membrane is inversely proportional to the gap height squared. Thus, according to some embodiments, tall electrodes **914** can be placed at the outer regions of the structure **902**. Using such a configuration, the membrane displacement can still be detected optically while the tall side electrodes are manufactured to be tall enough, or otherwise positioned, such that they are close to the membrane to enable the electrostatic actuation of the membrane. Such electrostatic actuation can be controlled by a controller **916**, for example. Some embodiments of device **900** could include a controller for providing an electrical bias to the reflective diffraction grating **908** as described in previous embodiments. Such embodiments having controller for providing electrical biases to the diffraction grating **908** and/or structure **904** can, for example, controllably adjust a feature of the reflective diffraction grating **908** and/or structure **904**.

Yet another embodiment for increasing the sensitivity of the sensor devices is to create an open-gap (i.e. open-cavity) structure. For example, FIGS. **10**, **11**, and **12** depict a device

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1000 having such an open-gap structure. Specifically, FIG. 10 is a side, cut-away view of the sensor 1000. FIGS. 11 and 12 provide a top-down view of device 1000, where FIG. 11 depicts a rectangular-shaped embodiment and FIG. 12 depicts a circular-shaped embodiment.

Device 1000 includes a mechanical structure 1002 (i.e. a membrane or beam) having a reflective surface as described in prior embodiments. However, unlike previous embodiments that incorporate a substantially sealed cavity, cavity 1006 of device 1000 is provided with one or more orifices to provide a passage for air to flow between cavity 1006 and the surrounding environment outside of cavity 1006. Accordingly, with this structure, the air can move freely in and out of these orifices, and the decrease in mechanical sensitivity caused by air compression or vacuum is reduced.

Additionally, because the temperature of the air in cavity 1006 can affect the mechanical properties of structure 1002, it can be advantageous to vent any heat buildup within the cavity. Accordingly, allowing air to freely flow into and out of the cavity through the one or more orifices can mitigate such heat buildup (e.g. from heat introduced by a light source).

To achieve the open-gap structure, any wall that forms the cavity 1006 can include one or more orifices for providing the passage of air between the inside and outside of cavity 1006. For example, the structure 1002 can be perforated with holes or slits 1008, side walls 1010 can be perforated with holes or slots 1012, and/or substrate 1004 can be perforated with holes or slots 1014. For embodiments incorporating a back-side cavity (i.e. sensors 200 and 300 of FIGS. 5 and 6), the air-release channel 382 of sensor 300 (FIG. 6) can be included to additionally provide an open gap structure in the back-side cavity.

According to some embodiments, the orifices can be located in a position or region of the cavity wall that will not interfere with the optical sensing of device 1000. For example slots 1008 are positioned in a portion of the structure 1002 that is outside of the portion of the structure 1002 used for reflecting the incident light that passes through reflective grating 1006 and is ultimately measured by a photo detector (not shown). Likewise, some embodiments may position slots 1014 in a portion of the substrate 1004 such that the incident light transmitted toward the reflective diffraction grating from below the substrate is not adversely disturbed.

It should be understood that some embodiments of device 1000 may include a controller for providing an electrical bias to the reflective diffraction grating 1016 and/or structure 1002, as described in previous embodiments. Such embodiments can, for example, controllably adjust a feature of the reflective diffraction grating and/or structure 1002.

It should be emphasized that the above-described embodiments of the present disclosure, are merely possible examples of implementations, merely set forth for a clear understanding of the principles of the invention. Many variations and modifications may be made to the above-described embodiment(s) of the invention without departing substantially from the spirit and principles of the invention. All such modifications and variations are intended to be included herein within the scope of the present invention and protected by the following claims.

The invention claimed is:

1. A device comprising:

- a phase-sensitive reflective diffraction grating for reflecting a first portion of an incident light and transmitting a second portion of the incident light such that the second portion of the incident light is diffracted;
- a mechanical structure having a first region and a second region, the mechanical structure positioned a distance d

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above the diffraction grating, the second portion of the incident light is reflected off of the first region of the structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light; and

an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

2. The device of claim 1, further comprising:

a controller coupled to the electrode and to the mechanical structure and configured to provide a voltage bias to at least one of the electrode and the mechanical structure.

3. The device of claim 2, wherein the controller is configured to electrostatically actuate the mechanical structure by providing the voltage bias.

4. The device of claim 1, wherein the mechanical structure forms a wall of a substantially sealed cavity.

5. The device of claim 4, wherein the electrode is positioned inside the sealed cavity and between the reflective diffraction grating and a side wall of the substantially sealed cavity.

6. The device of claim 1, wherein the distance that the electrode is spaced from the second region of the mechanical structure is selected to allow an electrostatic voltage to bias the structure.

7. The device of claim 1, further comprising:

a controller coupled to said reflective diffraction grating for controllably adjusting at least a first feature of said reflective diffraction grating.

8. The device of claim 7, wherein said controller controllably adjusts the distance d between the diffraction grating and the mechanical structure.

9. A method comprising:

illuminating a reflective diffraction grating with an incident light, the diffraction grating being positioned a distance d from a mechanical structure having a first region and a second region, a first portion of the incident light being reflected and a second portion of the incident light transmitted through the diffraction grating such that the second portion of the incident light is diffracted; reflecting the second portion of the incident light off of the first region of the mechanical structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light; and

applying a voltage bias to an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

10. The method of claim 9, further comprising:

actuating the mechanical structure by applying the voltage bias to the electrode.

11. The method of claim 9, further comprising:

controllably adjusting at least a first feature of said reflective diffraction grating by applying the voltage bias to the electrode.

12. The method of claim 11, further comprising:

adjusting the distance d between the diffraction grating and the mechanical structure by applying the voltage bias to the electrode.

13. A device comprising:

means for illuminating a reflective diffraction grating with an incident light, the diffraction grating being positioned a distance d from a mechanical structure having a first region and a second region, a first portion of the incident light being reflected and a second portion of the incident light transmitted through the diffraction grating such that the second portion of the incident light is diffracted;

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means for reflecting the second portion of the incident light off of the first region of the mechanical structure such that an interference pattern is formed by the reflected first portion and the reflected second portion of the incident light; and

means for applying a voltage bias to an electrode extending toward, but spaced a distance away from, the second region of the mechanical structure.

14. The device of claim **13**, further comprising:

means for actuating the mechanical structure by applying the voltage bias to the electrode.

15. The device of claim **13**, further comprising:

means for controllably adjusting at least a first feature of said reflective diffraction grating by applying the voltage bias to the electrode.

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16. The device of claim **15**, further comprising:

means for adjusting the distance d between the diffraction grating and the mechanical structure by applying the voltage bias to the electrode.

17. The device of claim **13**, wherein the mechanical structure forms a wall of a substantially sealed cavity.

18. The device of claim **17**, wherein the electrode is positioned inside the sealed cavity and between the reflective diffraction grating and a side wall of the substantially sealed cavity.

19. The device of claim **13**, wherein the distance that the electrode is spaced from the second region of the mechanical structure is selected to allow an electrostatic voltage to bias the structure.

* * * * *

UNITED STATES PATENT AND TRADEMARK OFFICE
CERTIFICATE OF CORRECTION

PATENT NO. : 7,440,117 B2
APPLICATION NO. : 11/405051
DATED : October 21, 2008
INVENTOR(S) : Degertekin et al.

Page 1 of 1

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Column 1, line 47, delete "(i.e. S_m" and replace with --(i.e., S_m--

Column 3, line 16, delete "of device" and replace with --of a device--

Column 6, line 5, delete "0th order" and replace with --0th order--

Column 6, line 45, delete "process and" and replace with --process, and--

Column 6, line 50, delete "process and" and replace with --process, and--

Column 7, line 13, delete "provides" and replace with --provide--

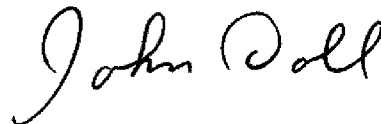
Column 7, line 15, delete "above substrate" and replace with --above the substrate--

Column 8, line 36, delete "for the forming" and replace with --for forming--

Column 13, line 34, delete "can me depos-" and replace with --can be depos- --

Signed and Sealed this

Tenth Day of February, 2009

A handwritten signature in cursive script that reads "John Doll".

JOHN DOLL
Acting Director of the United States Patent and Trademark Office