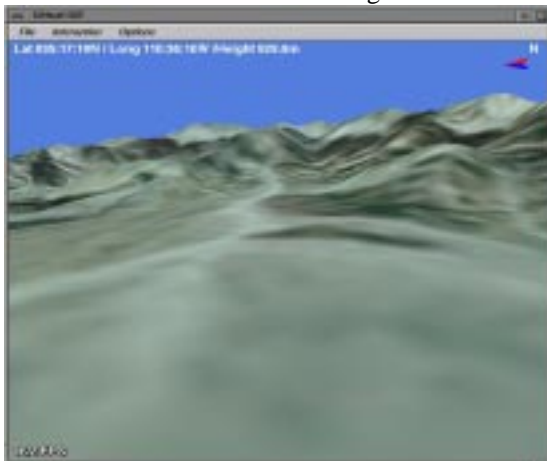Fig 1: Terrain management structure

Fig 2: After fly-in, without prediction
& without node skipping

Fig 3: Same as Fig 2, with prediction
& with node skipping

Fig 4: After fly-in, with random paging

Fig 5: Same as Fig 4, with prioritized center paging