

On Feedback Sets in Tournaments

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Abstract

In this report we consider the feedback vertex and arc set problems for tournaments. We first show NP-completeness of feedback vertex set for tournaments. We then give a simple 3-approximation algorithm for feedback vertex and arc sets.

1 Introduction

A *tournament* of size n is a complete graph on n vertices with edges having directions. In this article we follow the following conventions. An edge will be denoted by either (x, y) or $x \rightarrow y$. If $V \subset V(T_n)$, then $T(V)$ will represent the tournament induced by the vertices of V . Given a graph $G = (V, E)$ (directed or undirected), a feedback vertex (respectively arc) set for G is a subset X of $V(G)$ (respectively $E(G)$) if $G \setminus X$ is acyclic. For $v \in V(T_n)$, let $d(v)$ denote the out-degree of v , i.e. the number of vertices u such that (v, u) is in $E(T_n)$.

2 Feedback vertex set for tournaments is NP-Hard

It is well known [1] that the problem of finding a feedback vertex set of size at-most k is NP-complete for directed graphs. By the next result we show that the problem is NP-complete even when the digraphs are restricted to be tournaments.

Problem 1 (TFBVS). *Given a tournament T_n and a number k , does there exist a feedback vertex set of size at most k ?*

Theorem 2. *TFBVS is NP-complete.*

Proof. It is easily seen that TFBVS is in class NP. To show that it is actually NP-complete, we reduce the problem of vertex cover to it. Given a graph $G=(V, E)$,

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and a number k , we construct the graph $G' = (V', E')$ from it in the following manner. Let $V = \{v_1, v_2, \dots, v_n\}$. Define

$$\begin{aligned} V' &= \{v_{11}, v_{12}, v_{13}, \dots, v_{n1}, v_{n2}, v_{n3}\}. \\ E_1 &= \cup_{i=1}^n \{(v_{i1}, v_{i2}) \cup (v_{i3}, v_{i1}) \cup (v_{i3}, v_{i2})\}. \\ E_2 &= \cup_i \text{ adjacent to } j, i < j \{(v_{j1}, v_{i1}) \cup \{\cup_{(k,l) \neq (1,1)} (v_{ik}, v_{jl})\}\}. \\ E_3 &= \cup_i \text{ not adjacent to } j, i < j \{\cup_{(k,l)} (v_{ik}, v_{jl})\}. \\ E' &= E_1 \cup E_2 \cup E_3. \end{aligned}$$

Now we will show that there exist a vertex cover of size at most k in G iff there exist a feedback vertex set of size at most k in G' . Clearly a vertex cover of size at most k in G will act as a feedback vertex set of size at most k in G' . So let W' denote a feedback vertex set in G' . Let $W = \{v_i \in V : v_{ij} \in W'\}$. If this set is not a vertex cover in G , then there exist an edge, say (v_i, v_j) ($i < j$), such that neither v_{ik} nor v_{jl} is in W' . Thus there exist a cycle $\{v_{i1}, v_{i2}, v_{j3}, v_{j1}\}$ in G' , a contradiction. Hence we have shown that TFBVS is NP-complete. \square

Remark 3. *If we let TFBAS be the same problem for the arc set instead of the vertex set, we do not know whether it is NP-Hard and leave it as an open problem.*

3 Approximation Algorithms for Feedback Sets in Tournaments

The best known approximation algorithm for feedback sets in general directed graphs is $O(\log n \log \log n)$ due to Seymour [3]. In this section we show that if the problem is restricted to tournaments, the approximation factor drops down considerably to 3.

Given a tournament T_n , a 3 cycle of it will be denoted by $a \rightarrow b \rightarrow c \rightarrow a$, with a, b, c being distinct vertices of T_n . We first need a simple lemma which will give us the desired approximation factor.

Lemma 4. *Let T_n be a tournament and C_k ($3 \leq k \leq n$) be a cycle in T_n . Then there exists a 3 cycle C_3 in T_n such that $V(C_3) \subseteq V(C_k)$.*

Proof. The proof is by induction on k . If $k = 3$, there is nothing to prove. So let C_k have at-least 4 distinct vertices. Let a, b, c be any three vertices in $V(C_k)$ which occur in C_k in that order. Then if $c \rightarrow a$, we have the 3 cycle $a \rightarrow b \rightarrow c \rightarrow a$. Otherwise by induction on C_{k-1} which is C_k with b removed and the edge $a \rightarrow c$ added, we are done. \square

So by the lemma above, the task of selecting vertices (resp. edges) to remove all cycles in T_n reduces to selecting vertices (resp. edges) to remove all 3 cycles in T_n . We formulate the TFBVS problem as the following integer program. Assign a 0/1 variable x_v for each $v \in V(T_n)$, the variable being 1 iff v is picked

in the feedback vertex set. Let \mathbf{C} denote the family of 3 cycles in T_n . Each $C \in \mathbf{C}$ is a 3 element subset of vertices of T_n . Now the TFBVS problem can be formulated as follows.

$$\begin{aligned} & \text{minimize} && \sum_{v \in V(T_n)} x_v \\ & \text{subject to} && \sum_{C: v \in C} x_v \geq 1, C \in \mathbf{C} \\ & && x_v \in \{0, 1\}, v \in V(T_n) \end{aligned}$$

Notice here that given a tournament T_n with out-degrees of vertices denoted by $d(v_1), \dots, d(v_n)$, the number of 3 cycles in it are exactly $\binom{n}{3} - \sum_{i=1}^n \binom{d(v_i)}{2}$, which is at-most $O(n^3)$. Hence the LP has size polynomial in n .

Let the optimal to this linear program be denoted by c^{OPT} . The LP relaxation of this problem is obtained by letting $0 \leq x_v \leq 1$ for all $v \in V(T_n)$. Notice here that the upper bound of 1 is redundant as it is a minimization problem and so can be dropped while solving the relaxed problem.

Now we find an optimal solution to the LP relaxation. Let X be the set of vertices whose corresponding variables are at-least $1/3$. We set these variables to 1 and others to 0 to get a feasible solution to the integer program. Moreover the cost of the solution obtained is at-most $3 \cdot c^*$ which is at-most $3 \cdot c^{OPT}$. Hence we have a 3 approximation to TFBVS. For further details on the technique used above the reader is referred to [2].

Remark 5. *Essentially the same idea gives a 3 approximation to TFBAS. Moreover if the vertices or edges have weights, still the same approximation factor works. This is because each constraint in the LP will still have 3 variables.*

Remark 6. *If we consider a slightly general problem of finding a feedback set, which can consist of both the edges and the vertices (possibly having weights), then the same technique yields a 6 approximation algorithm for it. This is because each constraint in the LP corresponding to the problem will have 6 variables.*

References

- [1] M.R.Garey and D.S.Johnson, Computers and Intractability: A guide to the theory of NP-completeness, Freeman and Company (1979).
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- [3] P.D.Seymour, Packing directed circuits fractionally, Combinatorica 15:281-288.