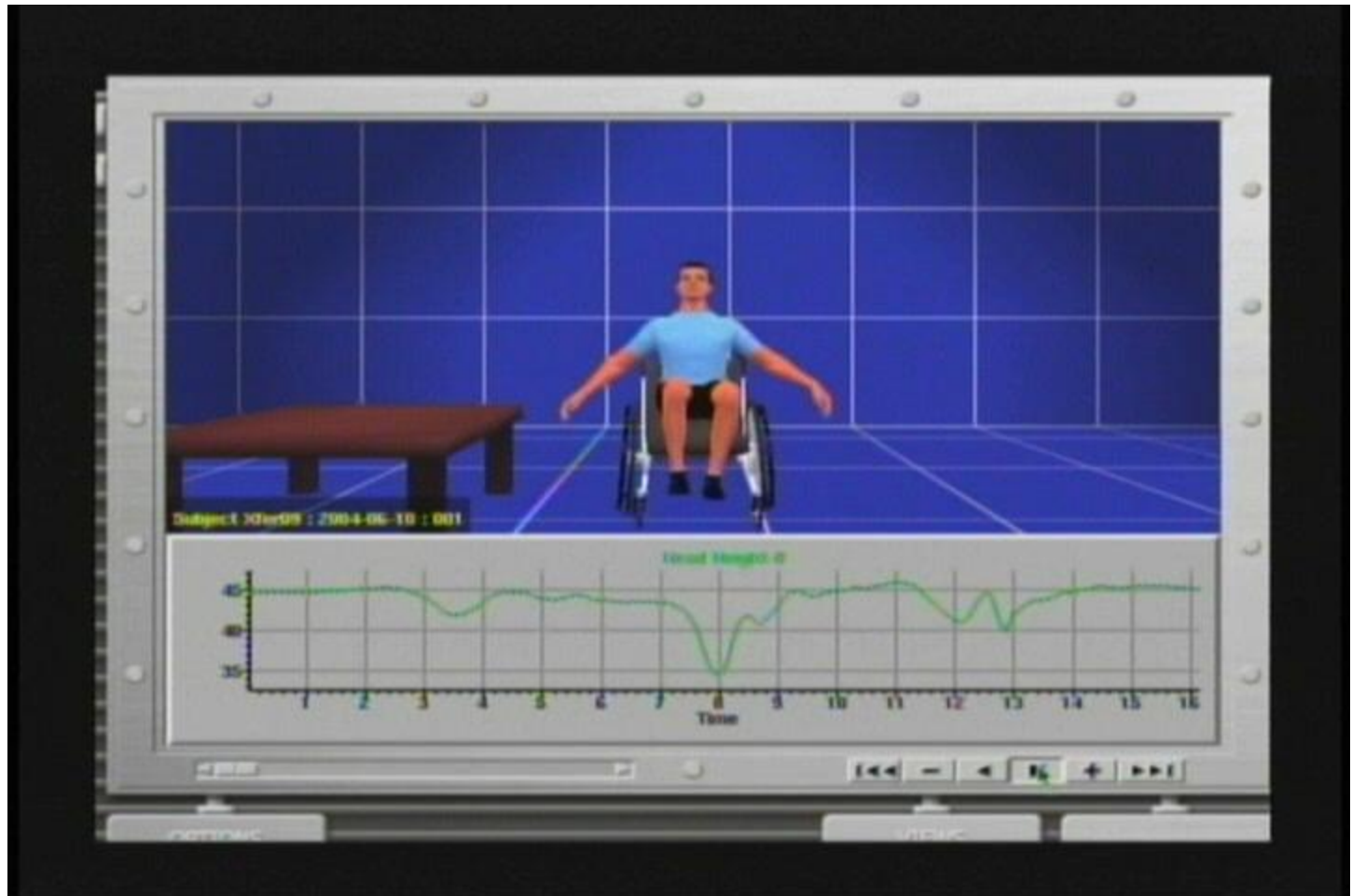




# Kinematics of Lateral Transfers: A Pilot Study

Sharon Sonenblum, ScM  
Thursday, August 4<sup>th</sup>, 2005

# What is a lateral transfer?





# Background

- Lateral transfers are very important to the independent function of a manual wheelchair user. It is believed that a better understanding of the kinematics would lead to improved clinical training and interventions.
- Current Research is limited
  - Multiple studies have addressed upper extremity kinematics during transfers, but do not address the overall strategy used to perform the transfers (*Finley et al, Perry et al, etc*)
  - Two studies of full body kinematics – but neither looked at the more frequently used lateral transfers.
    - long-sitting transfers (2 views, mostly quadriplegic) (*Allison et al*)
    - posterior transfers (*Gagnon et al*)



# Research Goals

- Kinematic description of transfers
- Identify transfer strategies (and how they are influenced by injury level and demographics)
- Long Term:
  - Identify the safest and most efficient transfer strategies for different people
  - Inform clinicians for improved and personalized transfer training



# Methods: Subjects

- Convenience sample of 19 male adults with IRB approval and subject consent
- Transfer independently or with minimum assistance
- No pressure sores or upper extremity orthopaedic conditions



# Methods: Protocol

- Subjects transferred towards their stronger side from their wheelchair to 20" therapy mat and back.
- Repeat for 3 trials
- All 3 motion captured and analyzed
- At least one transfer videotaped

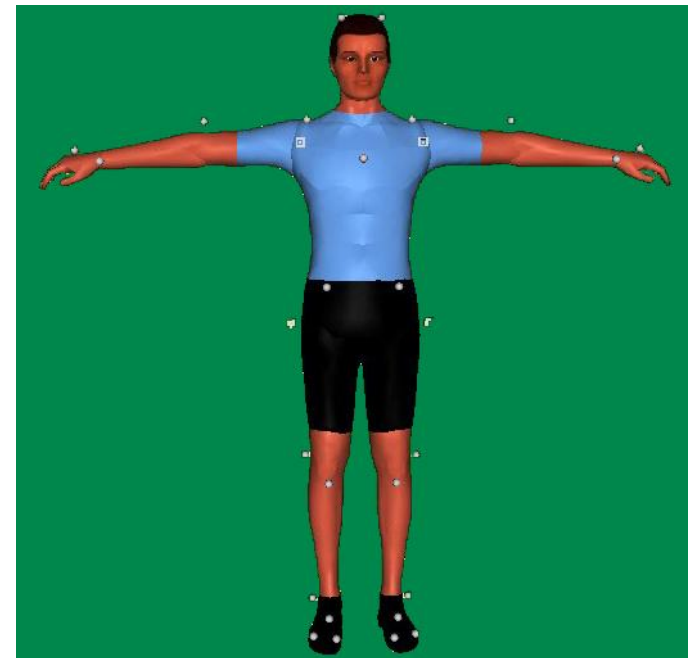
# Methods: Motion Capture

## *Instrumentation*

- Proprietary Software by Motion Reality Inc. (Marietta, GA)
- 8 – 60Hz cameras
- 41 markers on the body; 8 markers on the wheelchair

## *Capture*

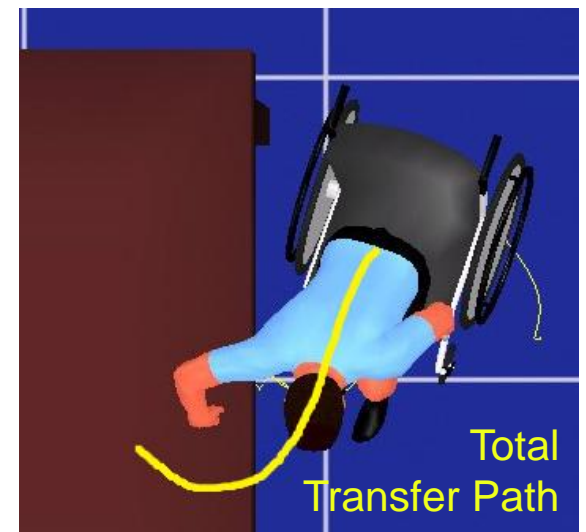
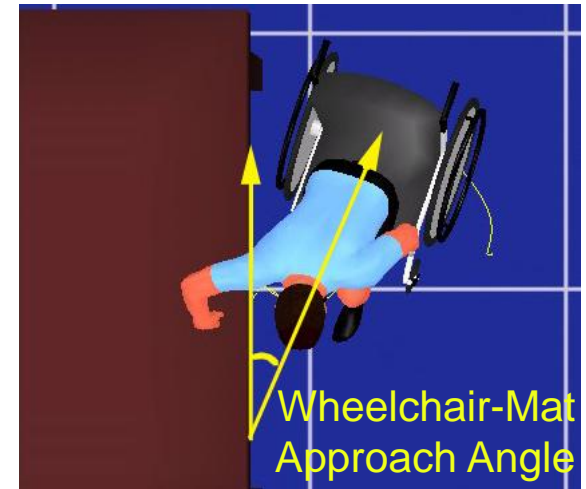
- Modified T-Pose, height, and weight to scale model
- Capture performs real-time best fit of visible markers to scaled model
- Tracks model body segments rather than joint centers





# Analysis: Kinematic Variables

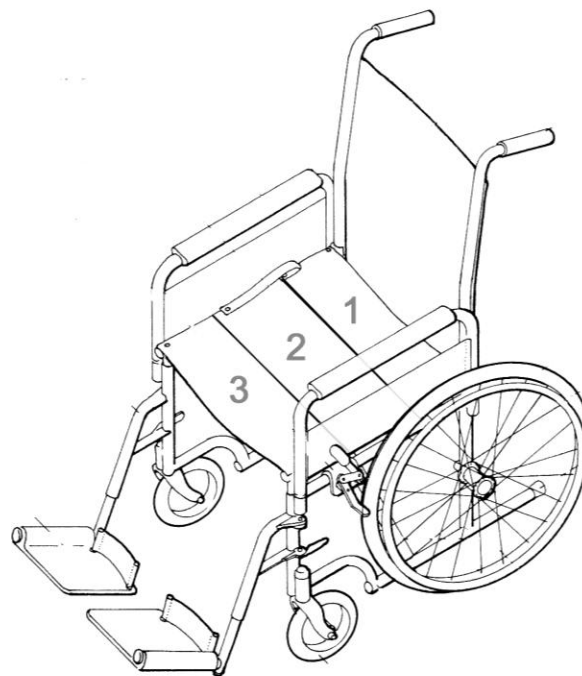
- Trunk Flexion
- Trunk Rotation
- Elbow Flexion
- Wheelchair-Mat Approach Angle
- Total Transfer Path
- % Transfer Path at Max Buttocks Elevation





# Methods

- Distance from back of wheelchair at final liftoff
- Hand position on wheelchair:
  - To Mat
    - Arm Rest
    - Seat Rail
    - Wheel
    - Cushion
    - Back Rest
  - To Chair
    - Arm Rest
    - Cushion
    - Seat Rail





# Analysis: Statistics

- Paired t-tests: to compare kinematic variables for transfers to and from wheelchair
- General Linear Model: predict kinematic variables based on the subject demographics and starting positions



# Results: Subjects

14 subjects analyzed:

(3 sliding boards and 2 cervical injuries were excluded)

Age	32 years (18-50)
Body Mass Index (BMI)	23 (20-32)
Arm Length (inches)	28" (21"-42")
Time Since Injury	12 years (3 months – 46 years)
Injuries	10 complete injuries (T3-T12) (most T9-T10) 3 incomplete thoracic injuries (T4, T6, T8) 1 incomplete post-polio



# Results: Subjects

- Only **time since injury** and **age** were highly correlated (0.88)
- *Time since injury vs. BMI (-0.51)*
- *Injury Level vs. BMI (0.53)*

# Average Kinematics

Kinematic Variables	Transfer from Wheelchair to Mat	Transfer from Mat to Wheelchair	p-value
	<i>Average (Range)</i>	<i>Average (Range)</i>	
Max Trunk Flexion (deg)	54 (31-73)	55 (37-73)	p>0.1
Max Trunk Rotation (deg)	23 (11-38)	23 (11-37)	p>0.1
Max Elbow Flexion - Leading Arm (deg)	89 (62-122)	82 (53-116)	p=0.009
Max Elbow Flexion - Trailing Arm (deg)	92 (47-130)	84 (57-113)	p=0.037
Wheelchair-Mat Approach Angle (deg)	22 (1-42)	24 (2-45)	p=0.061
Percent Path at Maximum Buttocks Elevation	0.54 (0.3-0.7)	0.48 (0.2-0.7)	p=0.01
Total Transfer Path (inches)	31.2 (20.3-40.8)	31.6 (14.5-40.6)	p>0.1

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# Average Kinematics: Elbow Flexion

Max Elbow Flexion Greater from Wheelchair to Mat  
than Mat to Wheelchair

Leading arm:  $89^{\circ}$  vs.  $82^{\circ}$

Trailing arm:  $92^{\circ}$  vs.  $84^{\circ}$



Transfer to Mat



Transfer to Wheelchair

# Average Kinematics:

## Percent Path at Maximum Buttocks Elevation

Transfer to **mat** (Max at 54% path) in **blue**.

Transfer to **chair** (Max at 48% path) in **red**.



34 year old, T9



18 year old, T4

View of two men w/ similar BMI at maximum buttocks elevation.



# Results: Linear Model

5 variables can be predicted for transfers to and from the mat (separately) with  $R^2 > 50\%$

- Buttocks elevation
- Torso rotation
- Torso flexion
- Wheelchair/mat angle
- Total path

# Results: Linear Model

	Max Trunk Flexion	Max Trunk Rotation	Max Trailing Elbow Flexion	Total transfer path
Level of Injury	—		—	—
Arm Length		+	+	
BMI		—		—
Time Post Injury	—	—		—
Age		+		
Distance from back of chair	—		—	—
hand position	*	*		
R-squared	82%	68%	85%	69%

+ positive influence; — negative influence

\* contributes to the model, but because it is a discrete variable, the influence cannot be described as positive or negative

# Results: Linear Model

	Max Trunk Flexion	Max Trunk Rotation	Max Trailing Elbow Flexion	Total transfer path
Level of Injury	—		—	—
Arm Length		+	+	
BMI		—		—
Time Post Injury	—	—		—
Age		+		
Distance from back of chair	—		—	—
hand position	*	*		
R-squared	82%	68%	85%	69%

As **level of injury** increases (severity increases, function decreases) – There is less motion in terms of trunk and elbow flexion, and the total transfer path is shortened.

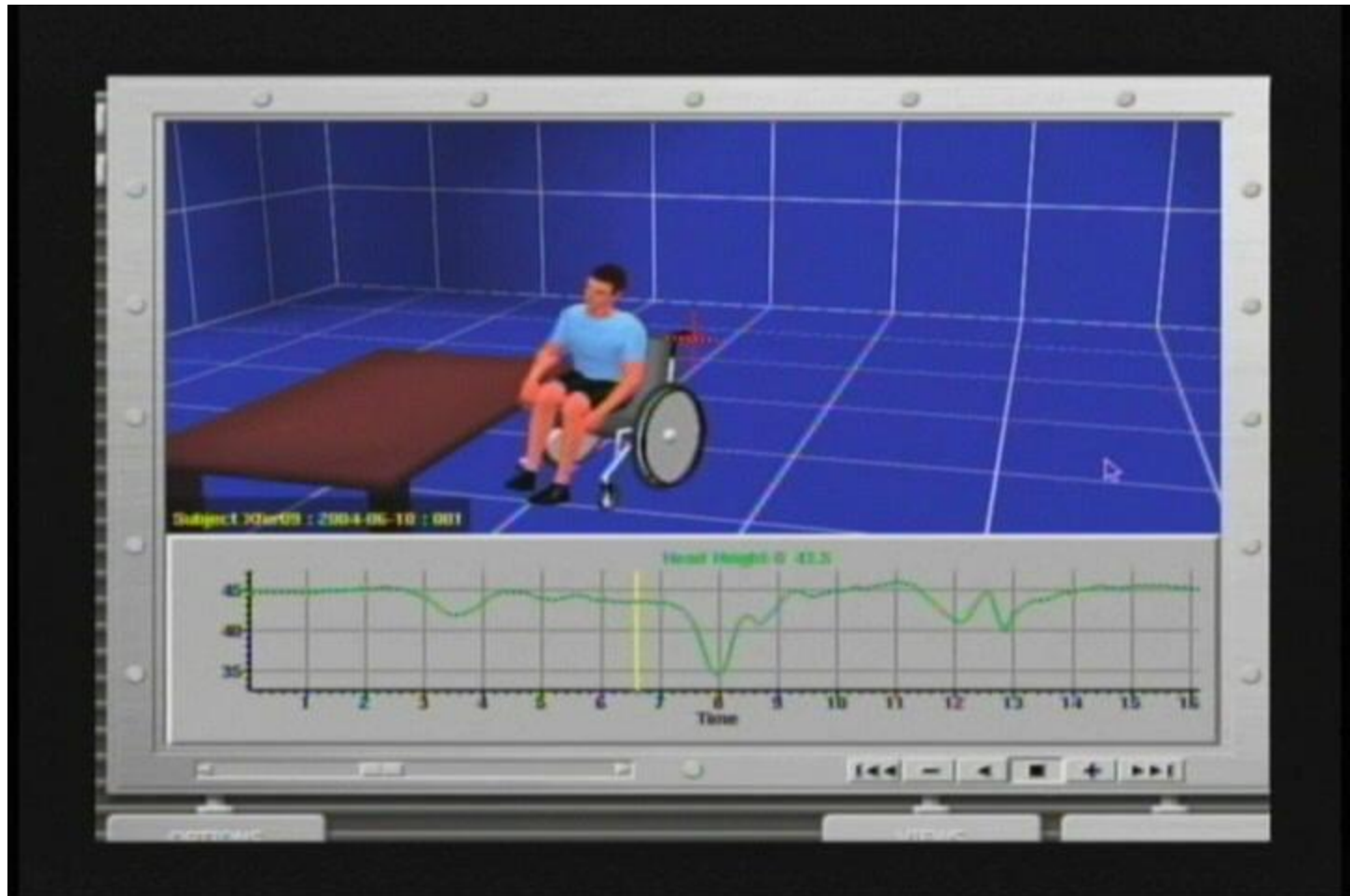
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As **time since injury** increases – There is less trunk motion (flexion and rotation), and the total transfer path is shortened.



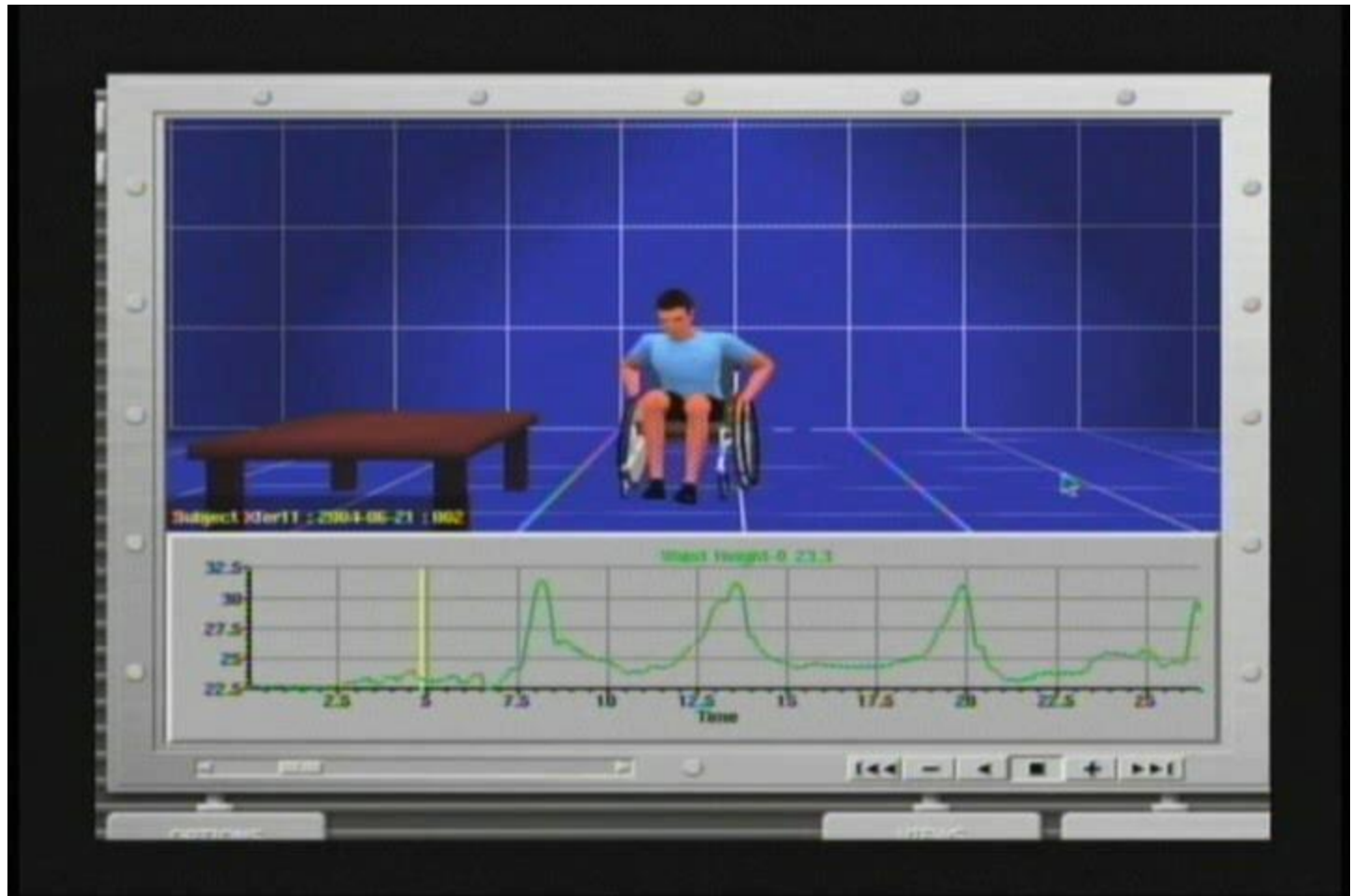
# Transfer to Mat (T9, 34yo)





# Another Transfer to Mat

(T6, 44yo, very similar BMI and arm length to previous transfer)




## A large, dark blue wheel with many spokes, resembling a bicycle wheel, set against a dark background. The wheel is positioned on the left side of the frame, with the spokes radiating outwards. The background is a solid dark blue, creating a monochromatic effect. The wheel's hub and spokes are detailed, showing the texture of the material. The overall composition is simple and graphic, focusing on the geometric form of the wheel.





# Conclusions and Future Work

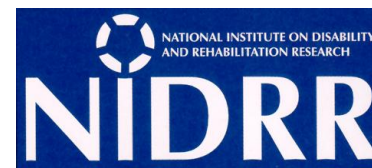
- Varied strategies
  - Pattern recognition and co-variance analysis to identify strategies
  - Cluster analysis
- 

# Acknowledgements

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Questions???