

## Parameter Estimation of Mechanistic Differential Equations via Neural Differential Equations

William Bradley, 4th Yr PhD Candidate (Boukouvala Lab)

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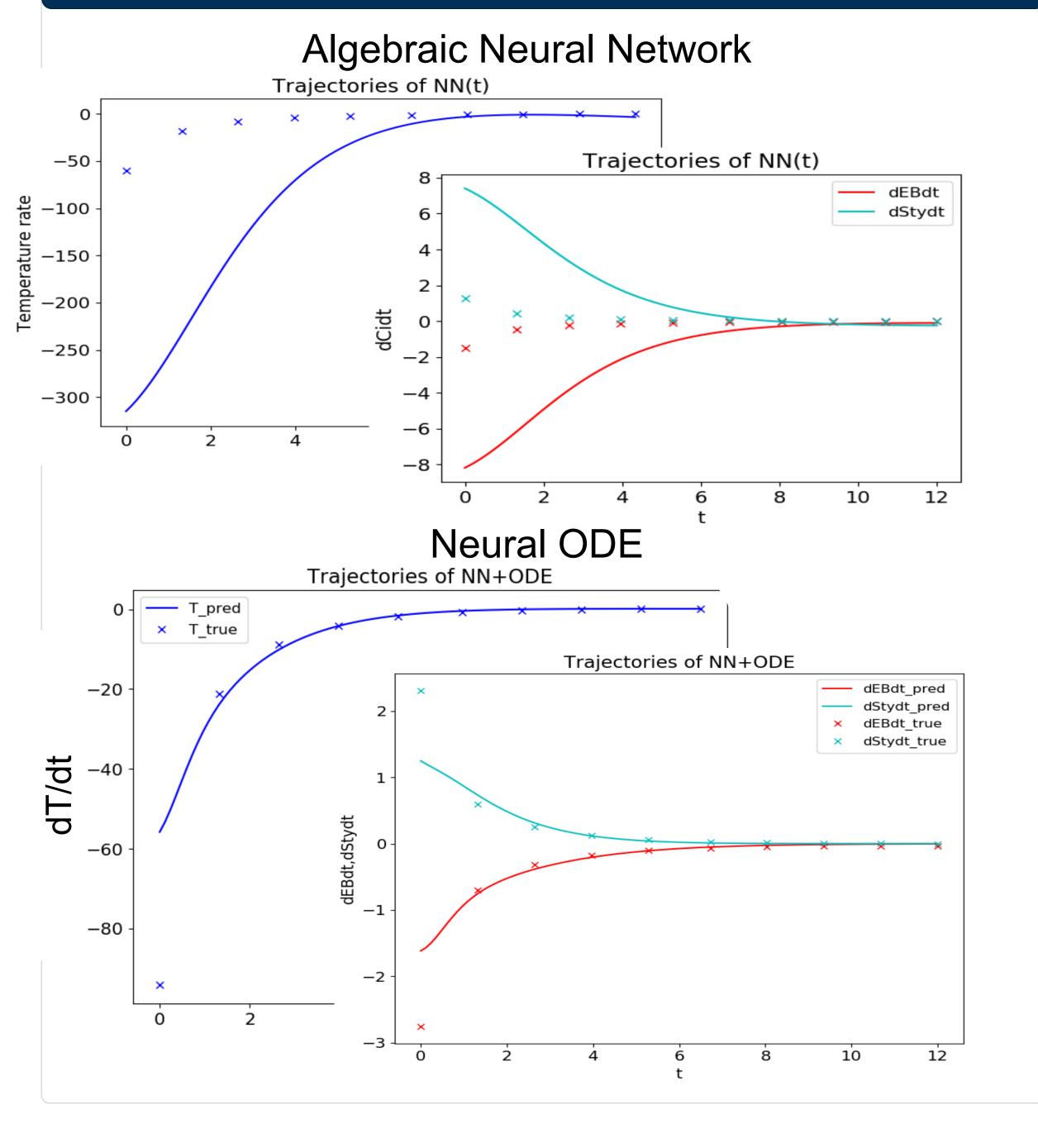
### Background Motivation

Regressing mechanistic models to experimental data can be intractable due to process nonlinearity and computation issues. Machine learning (ML) tools could reduce the cost of modeling building but offer limited interpretability/robustness. Using ML as a data-driven means to a mechanistic end, an indirect approach using NODEs is proposed that accelerates parameter estimation of mechanistic models.

### Objectives

- Compare ability of NODEs and NNs to estimate derivatives
- Compare performance of direct approach vs NODEbased indirect approach for fitting parameters

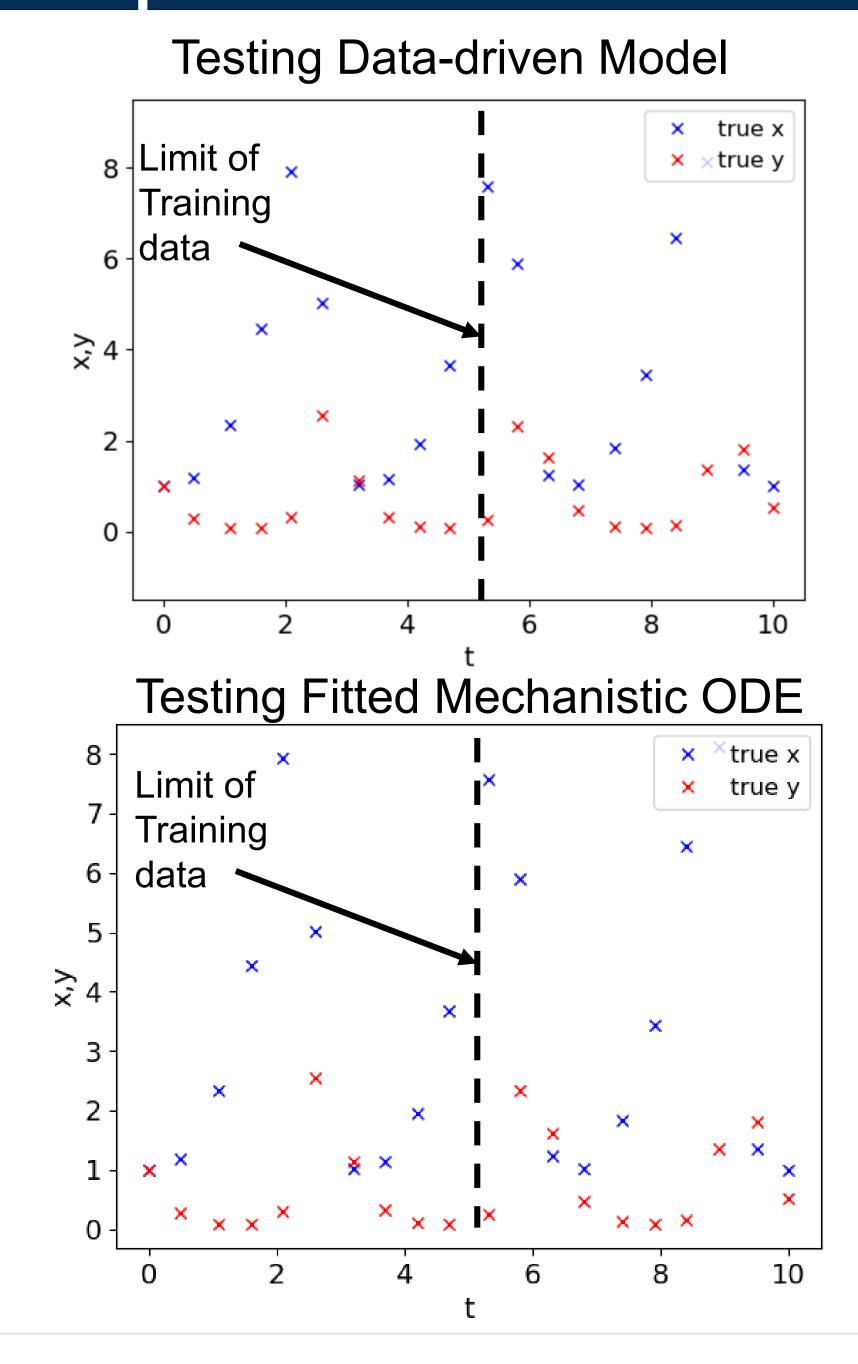
### Derivative Estimation: NN vs NODE



### Thesis

Data-driven models can be used to estimate parameters of mechanistic differential equations, accelerating creation of interpretable, generalizable (bio)chemical process models.

### Extrapolation: NODE vs MODE



# Collect Data Parameter Estimation of Neural ODE model X X Direct Indirect Approach Approach Approach Approach Mechanistic ODEs $\frac{dx}{dt} = ay + exp(bx)$ $\frac{dy}{dt} = cx^2y + \frac{d}{y}$ Step 3 Parameter Estimation of Compute derivatives from data-driven model

### **Indirect vs Direct Parameter Estimation**

	Lotka Volterra	Styrene Reactor	Penicillin fermenter
	(2 states, 3	(6 states, 3	(3 states, 11
	parameters, 20 dp)	parameters, 60 dp)	parameters, 90 dp)
Direct Approach	Total: 76 s	Total: 352 s	Did not converge
Indirect	Total: 62 s	Total: 116 s	Total: 183 s
NODE	Steps 1&2: 62. s	Steps 1&2: 110 s	Steps 1&2: 181 s
Approach	Step 3: 0.009 s	Step 3: 6.76 s	Step 3: 1.932 s

dp = data points NODE = Neural ODE

#### Conclusions

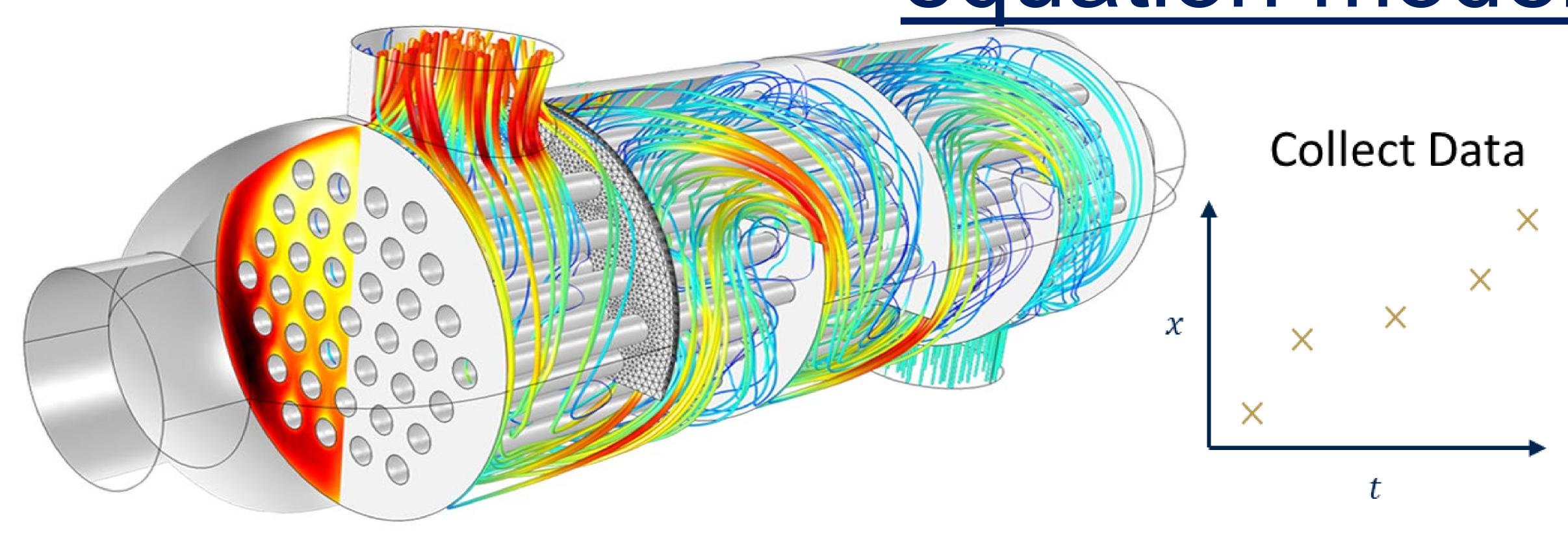
- NODEs estimate state derivatives more accurately than algebraic data-driven models
- Mechanistic ODEs have superior generalizability than Neural ODEs
- NODE Indirect approach can regress parameters of mechanistic models faster than direct approaches

### Acknowledgements

Georgia Tech Startup Grant RAPID/NNMI Grant #GR10002225



# Motivation: Parameter estimation of differential equation models



Direct Approach

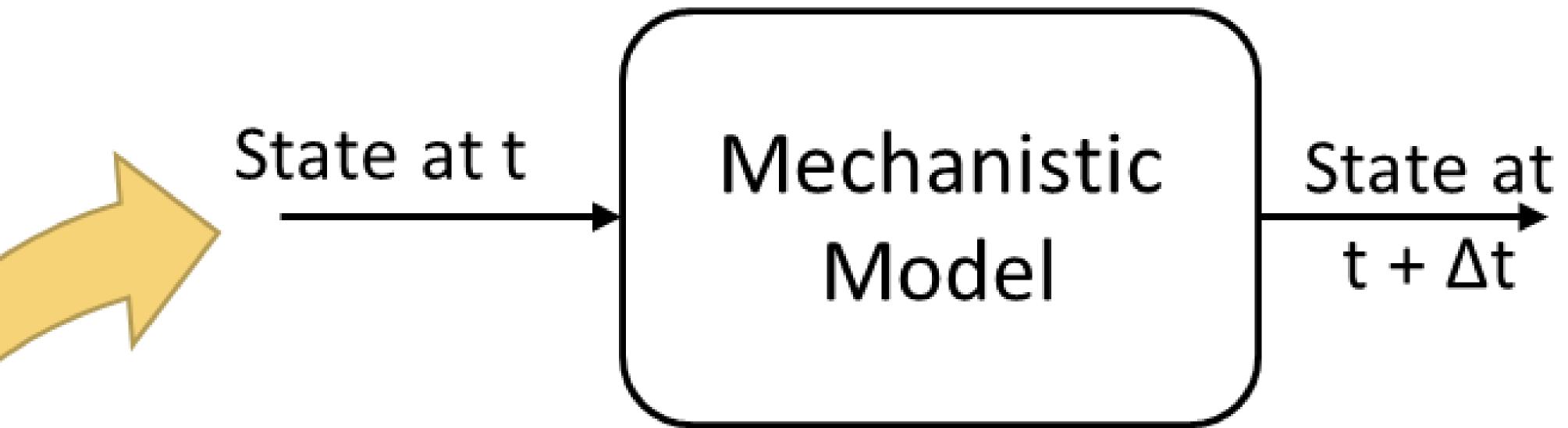
Parameter Estimation of Mechanistic ODEs

$$\frac{dx}{dt} = ay + exp(bx)$$

$$\frac{dy}{dt} = \frac{cx^2y + \frac{d}{y}}{y}$$

https://www.machinedesign.com/learning-resources/webinars/webinar/21134601/simulation-of-heat-exchangers

### Mechanistic Modeling (Domain Knowledge)



### Mechanistic (M) model

Advantages: High interpretability,

good extrapolation

Disadvantages: Computation intensive

### Machine Learning (Data Knowledge)

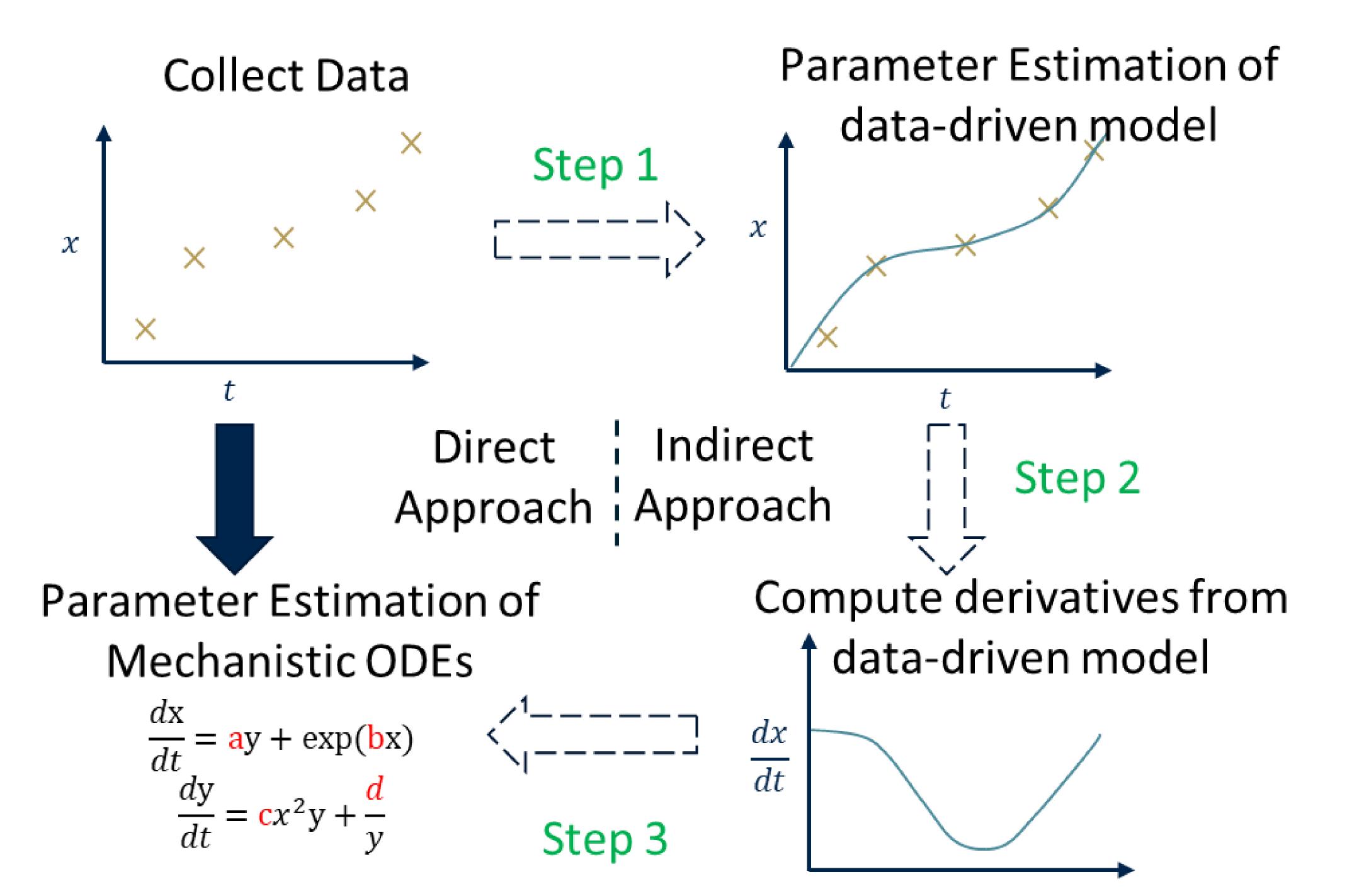
### Data-driven (DD) model

Advantages: Fast model-building

Disadvantages: Low interpretability,

poor extrapolation

### Proposed Method: Indirect Approach



### Hypotheses:

- Neural ODEs can predict derivatives better than Algebraic NN models
- A Neural ODE-based indirect approach can fit mechanistic ODEs faster and more accurately than a direct approach

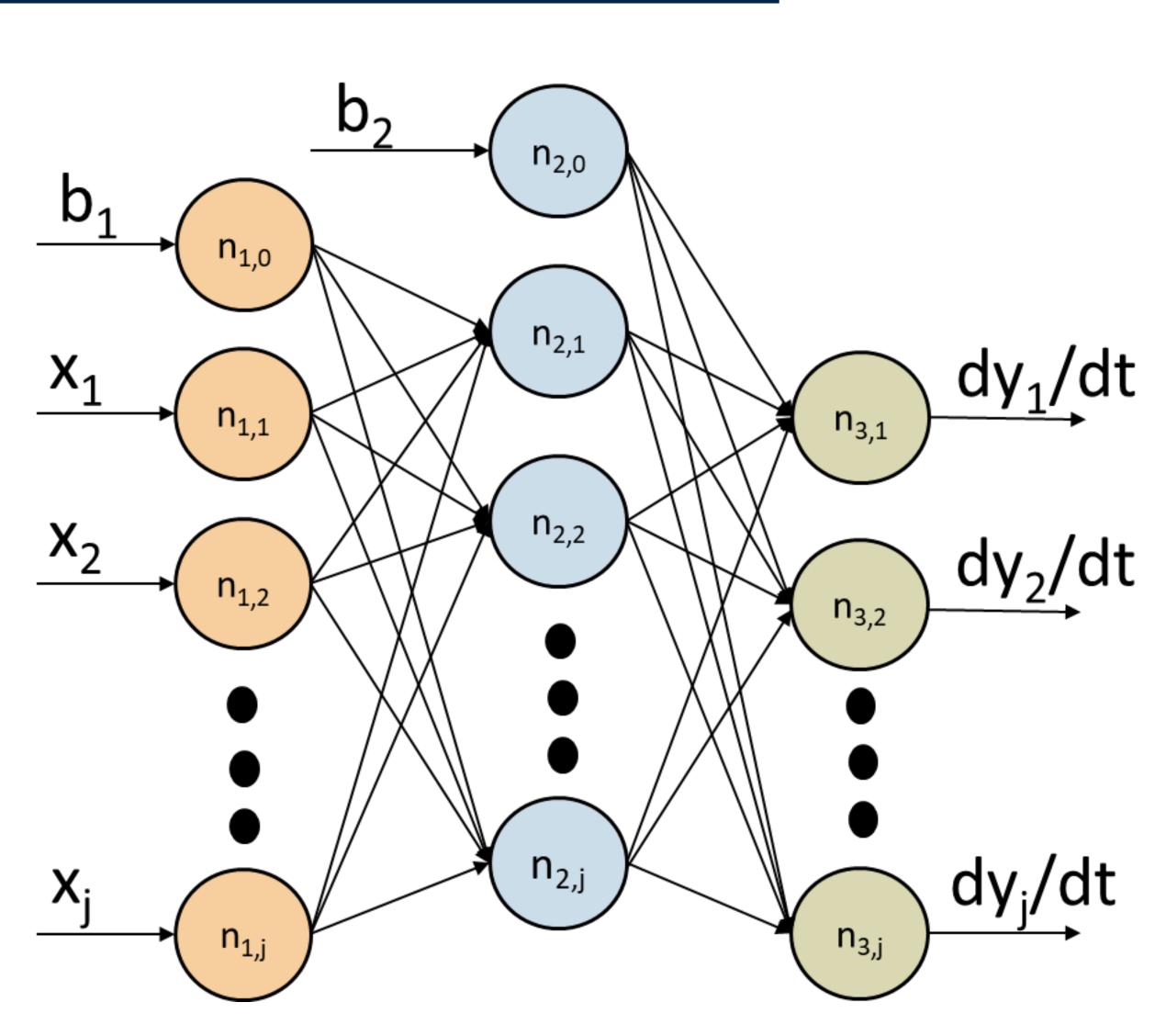
### Neural Ordinary Differential Equations (Neural ODEs)

 Neural Networks can approximate any nonlinear, continuous algebraic equation

$$y = NN(\sum_{k=1}^{S_{i-1}} w_{k,j}^{(i)} x_{(i-1),k} + b_{0,j}^{(i)})$$

 Neural ODEs can approximate nonlinear continuous differential equations

$$\frac{dy}{dt} = NN(\sum_{k=1}^{S_{i-1}} w_{k,j}^{(i)} x_{(i-1),k} + b_{0,j}^{(i)})$$



# Results: NN vs Neural ODE state estimates of styrene reactor

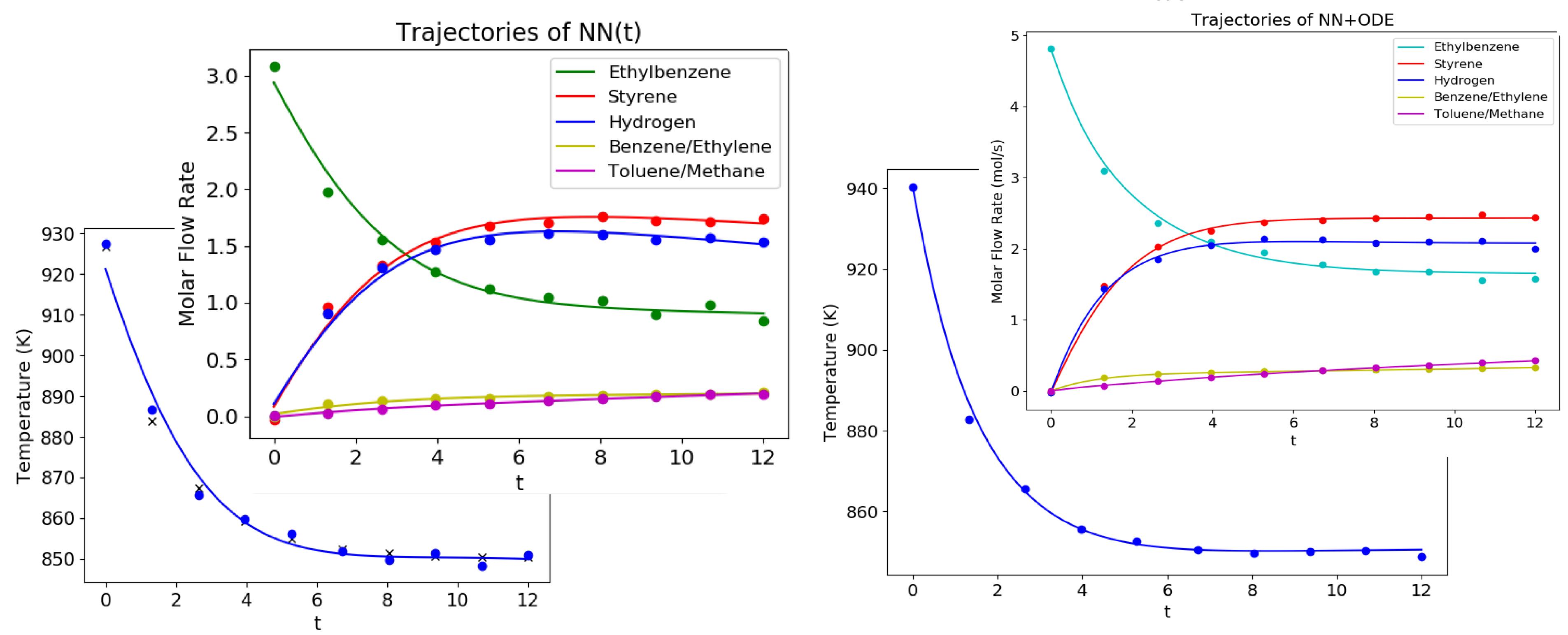
$$F_{EB}$$

$$F_{EB}, F_{Sty}, F_{H_2}$$

$$F_{Be}, F_{Tol}$$

Neural Network<sup>1</sup>: y = NN(t, w)

Neural ODE<sup>2</sup>: 
$$\frac{dy}{dt} = NN(x(t), w)$$

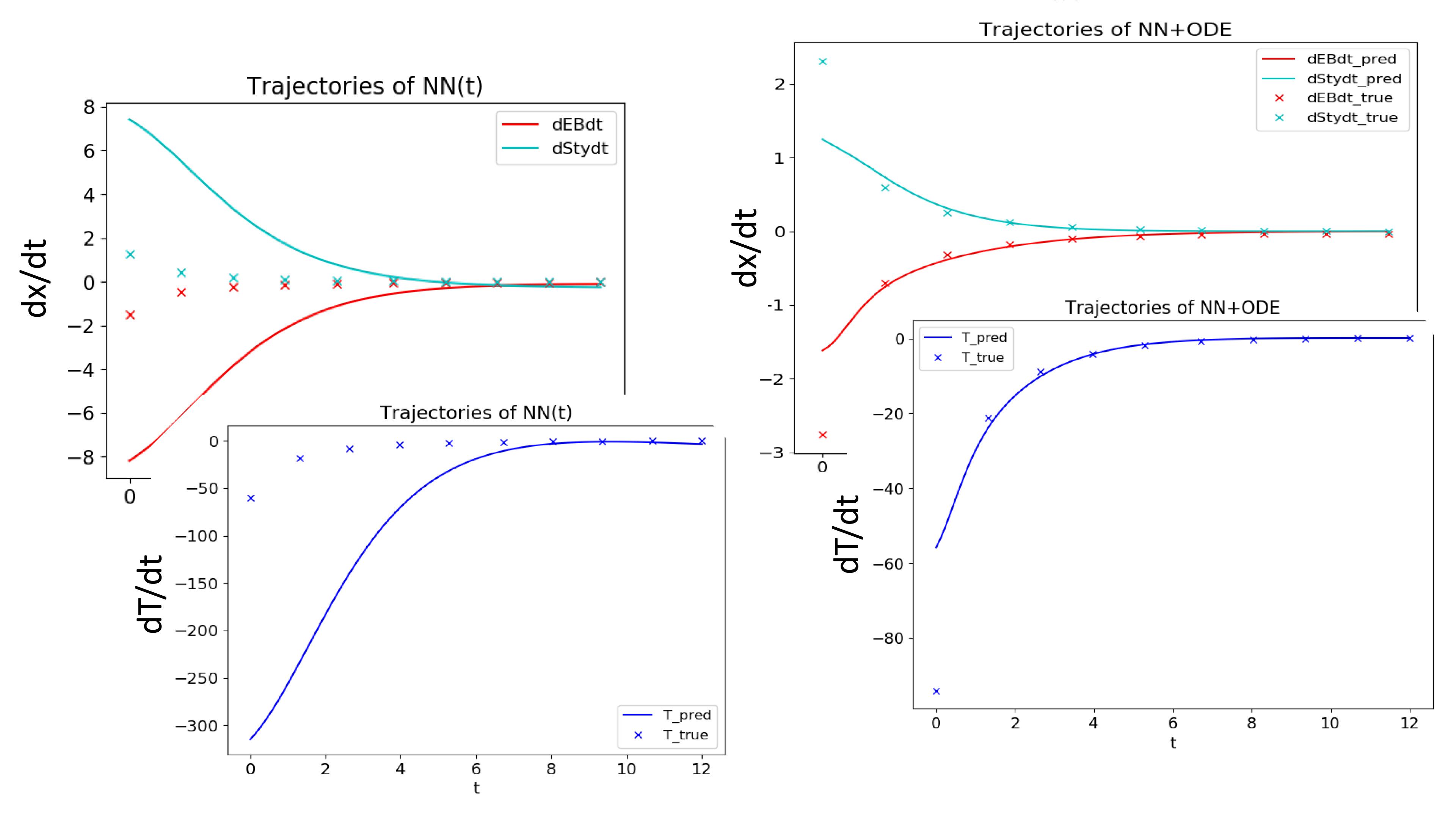


- 1) Cybenko, G. (1989). Approximation by superpositions of a sigmoidal function. *Mathematics of Control, Signals and Systems, 2*(4), 303-314. doi:10.1007/bf02551274
- 2) Chen, R. T. Q., Rubanova, Y., Bettencourt, J., & Duvenaud, D. (2018). Neural Ordinary Differential Equations. arXiv e-prints. Retrieved from https://ui.adsabs.harvard.edu/abs/2018arXiv180607366C

# Results: NN vs Neural ODE derivative estimates of styrene reactor

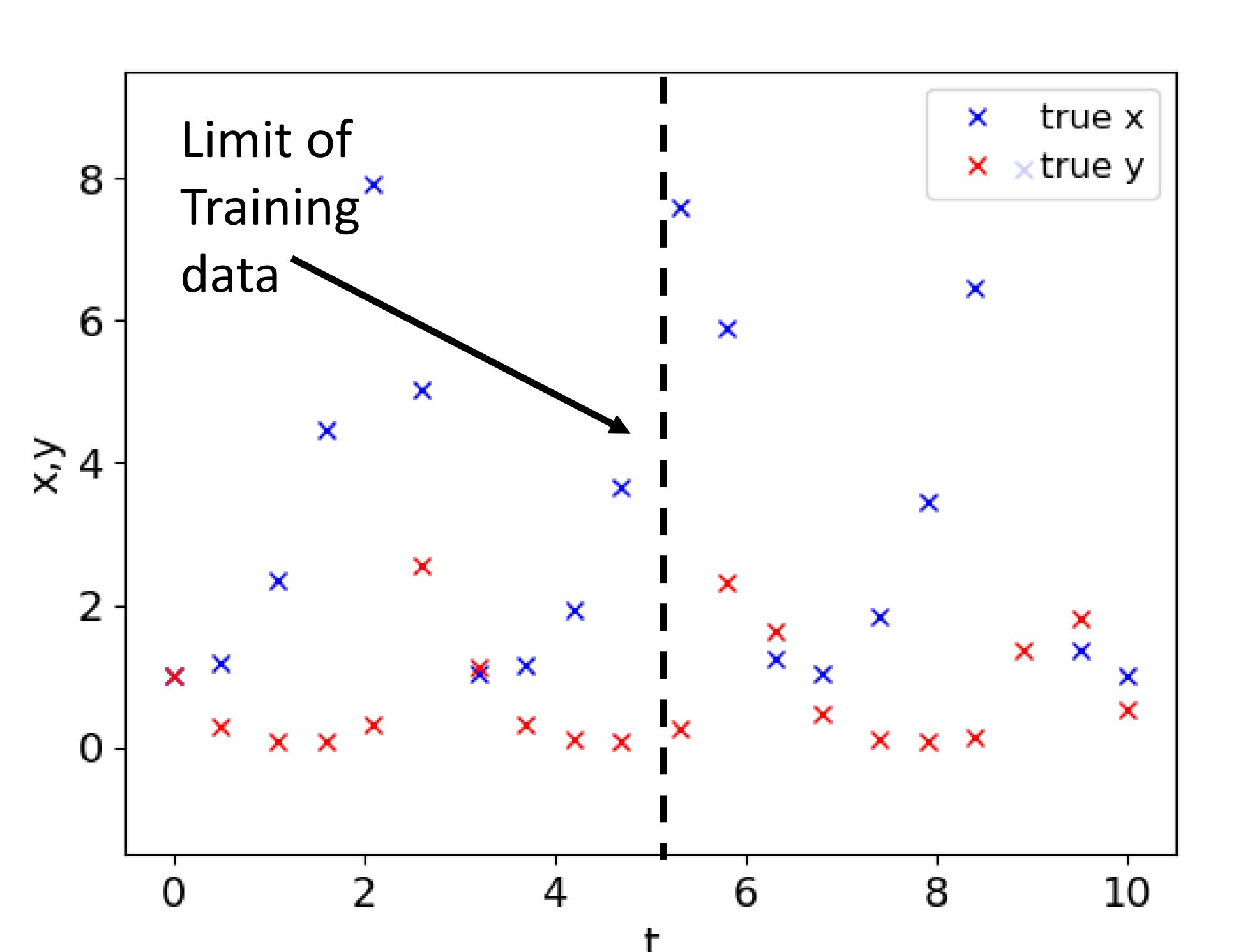
Neural Network: y = NN(t, w)

Neural ODE:  $\frac{dy}{dt} = NN(x(t), w)$ 

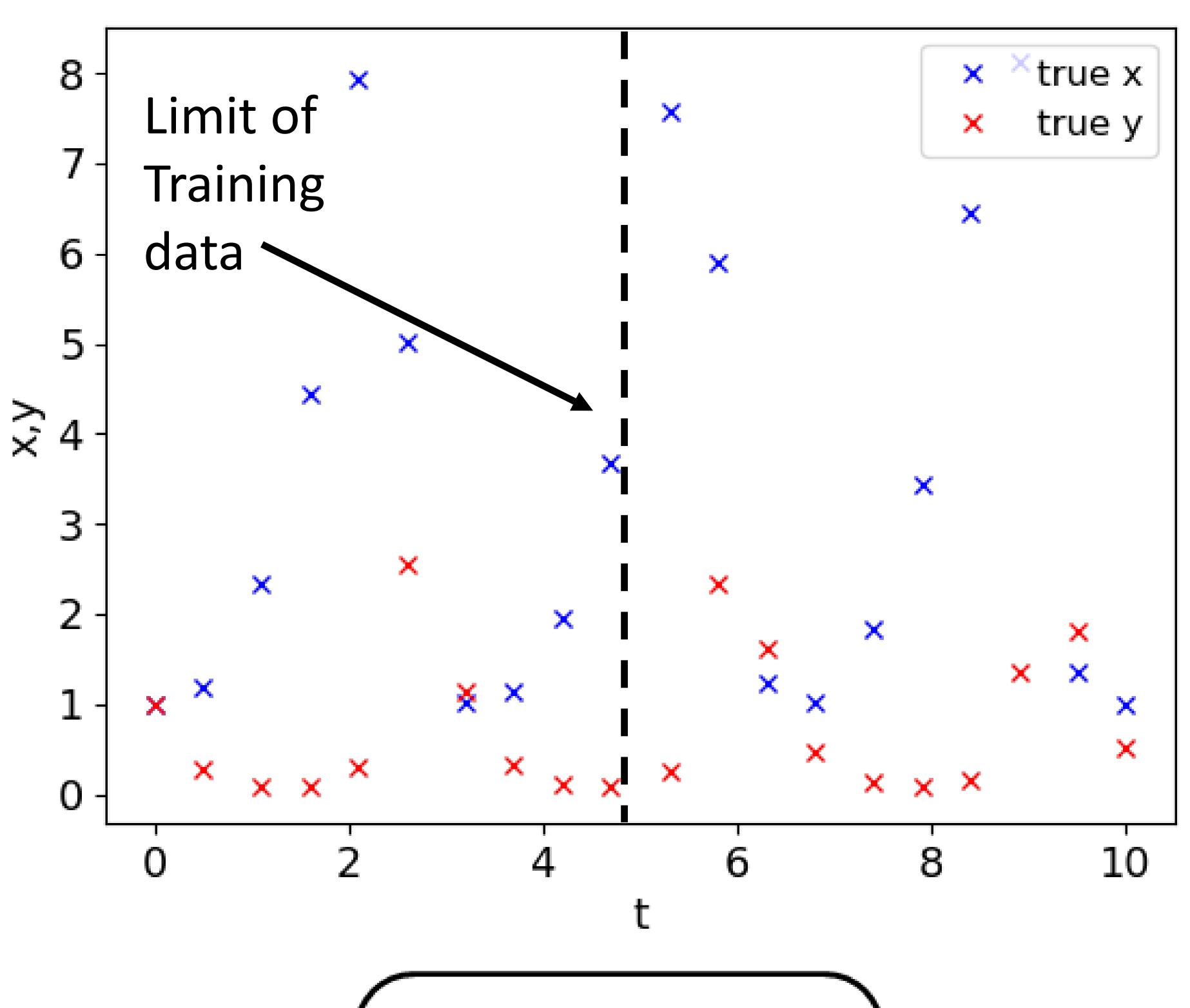


## Results: Extrapolation of NODE vs Mechanistic ODE

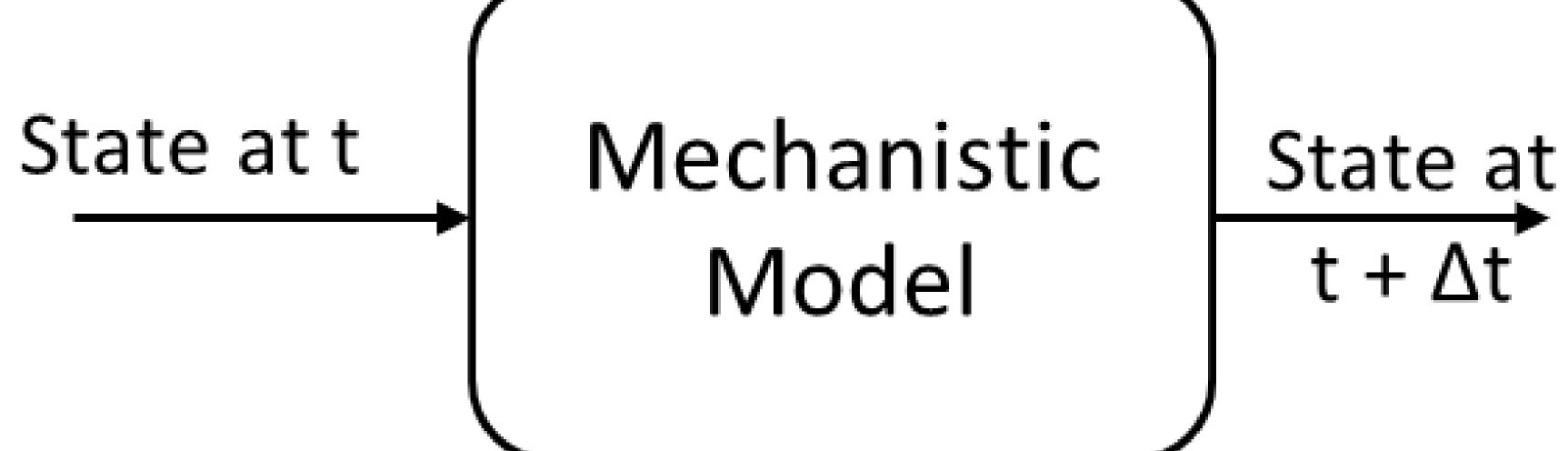
Testing NODE Model



Testing Fitted Mechanistic Model (parameters fitted w/NODE Approach)







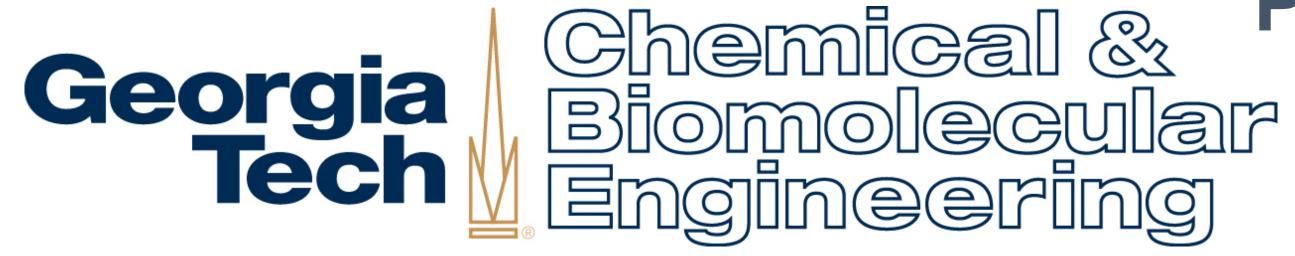
### Conclusions

	Predator-Prey System	Styrene Reactor	Penicillin Fermenter
	(2 states, 3 parameters,	(6 states, 3 parameters,	(3 states, 11 parameters,
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Direct Approach	Total: 76 s	Total: 352 s	Did not converge
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- Neural ODEs estimate state derivatives more accurately than algebraic data-driven models (e.g. Neural Networks)
- Mechanistic ODEs have superior generalizability than Neural ODEs
- NODE-based indirect approach can estimate parameters of mechanistic models faster than direct approaches



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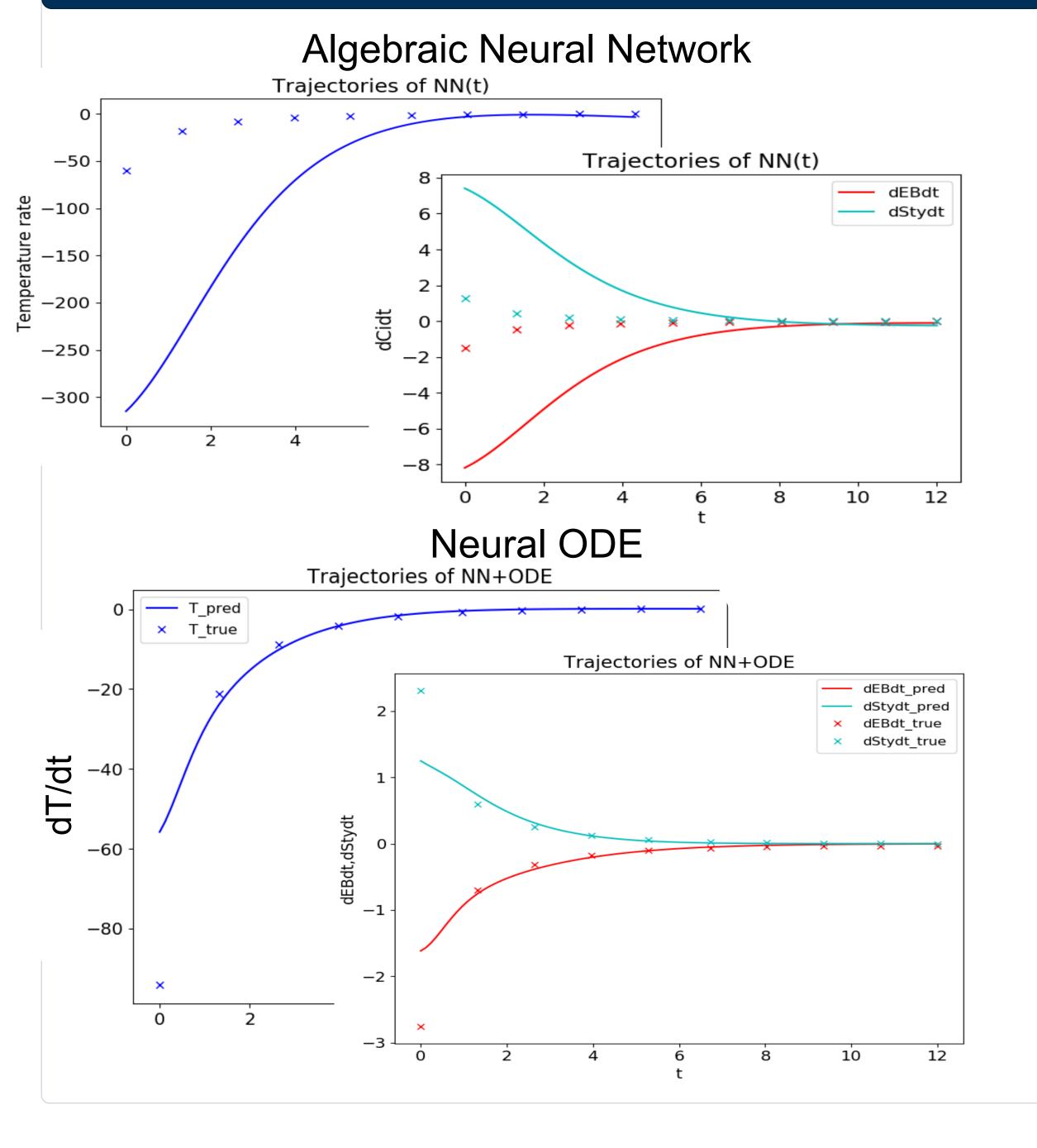
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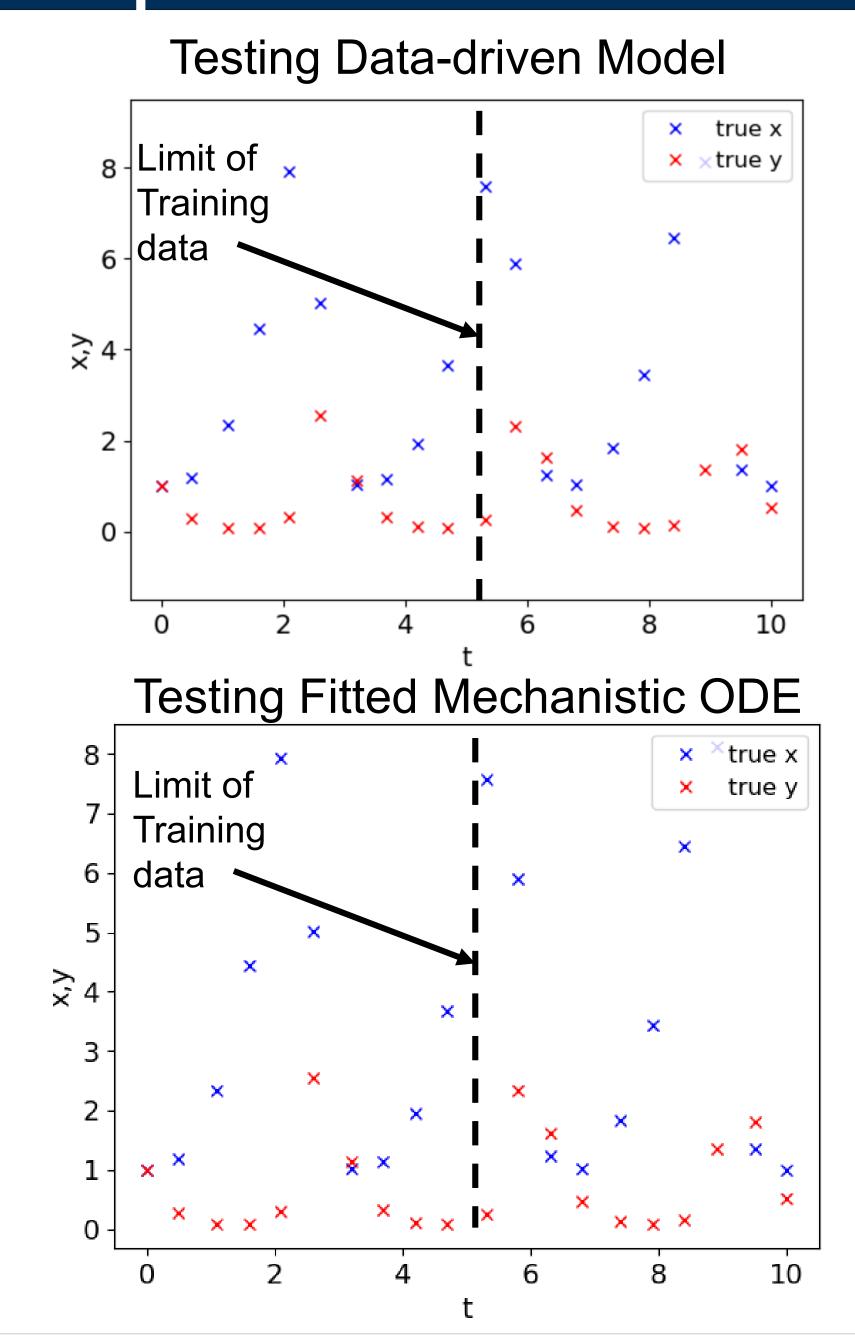
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#### **Indirect vs Direct Parameter Estimation**

Step 3

	Lotka Volterra	Ethylbenzene	Penicillin
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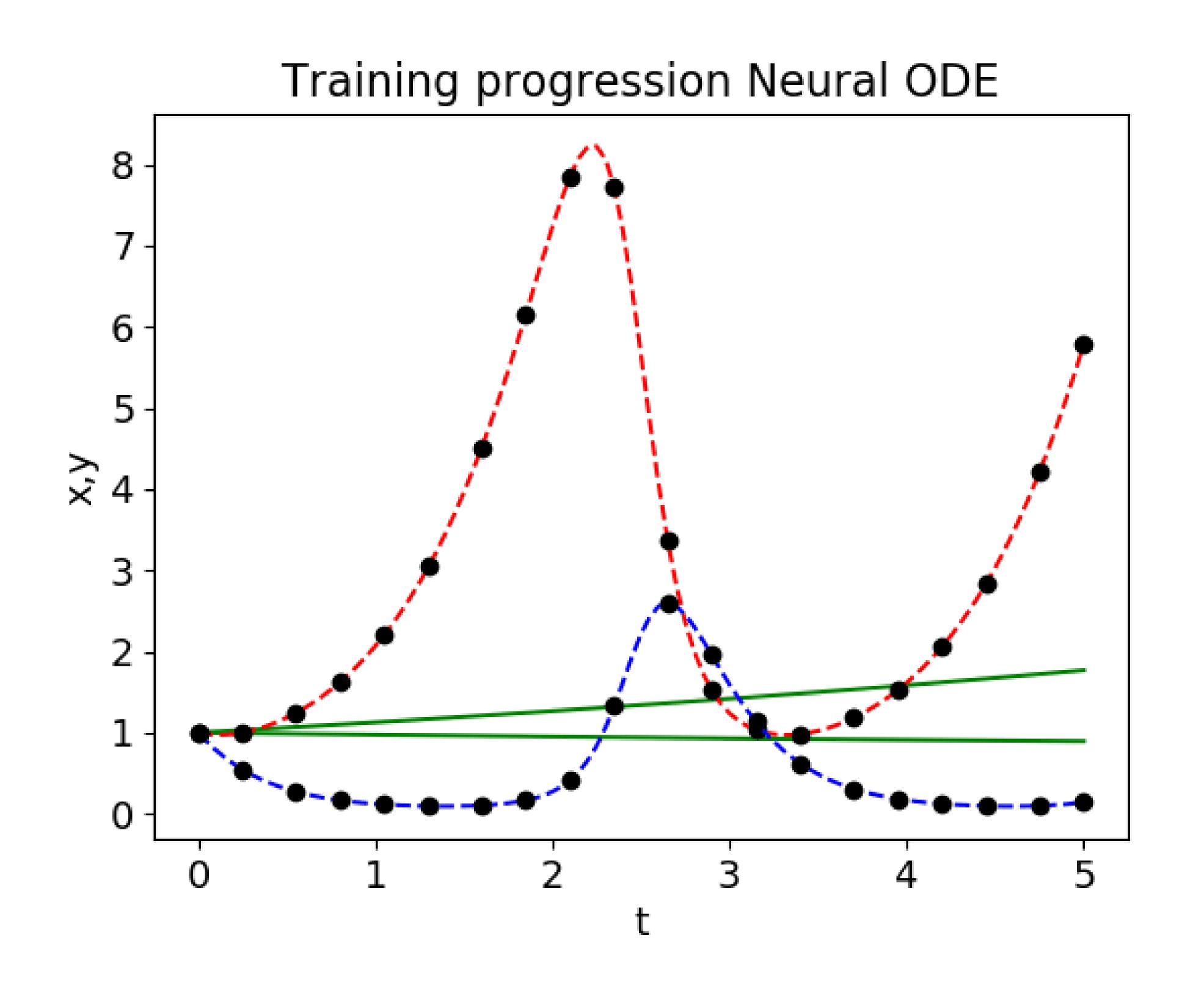
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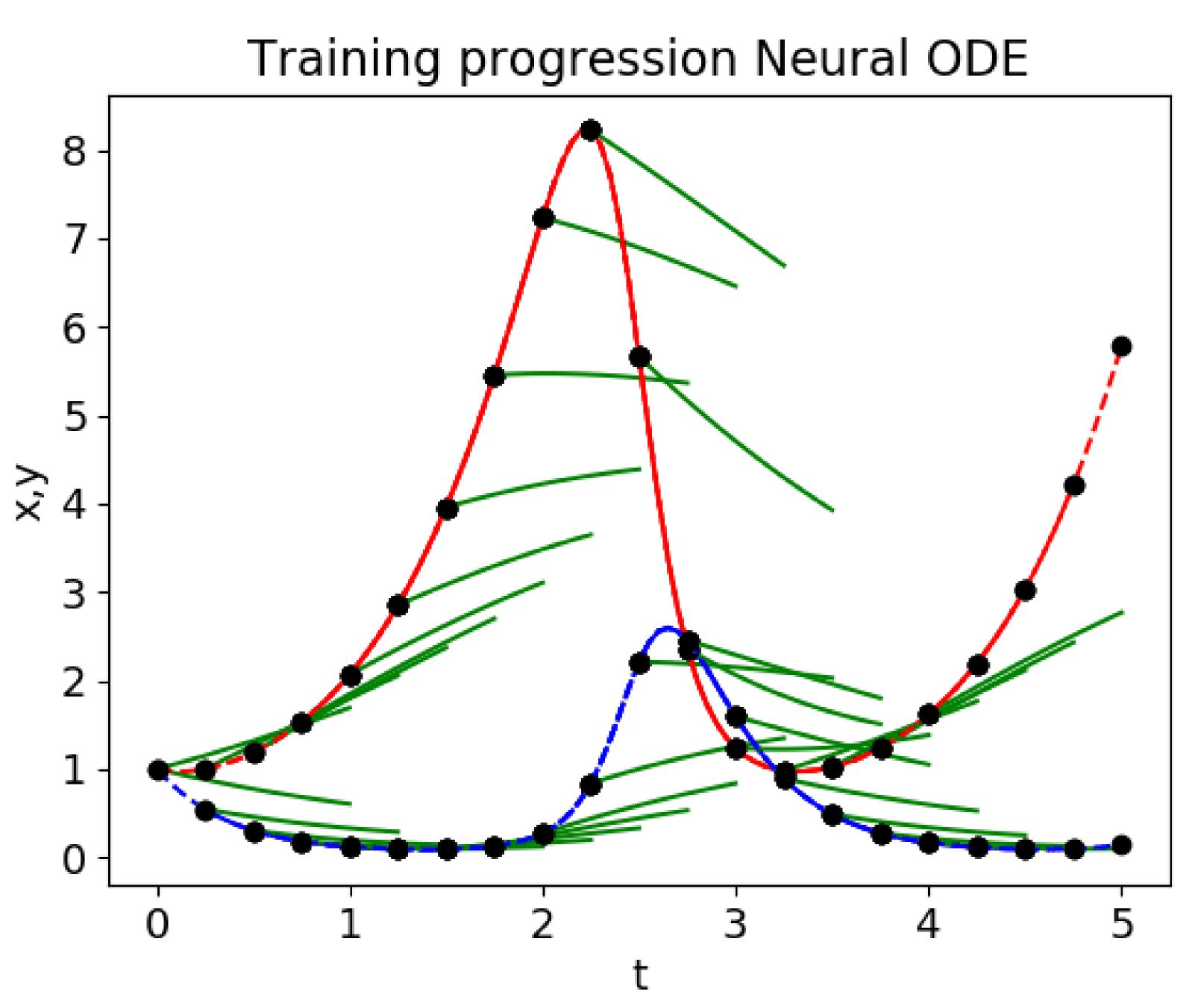
 $\frac{dy}{dt} = cx^2y + \frac{d}{v}$ 



## Extra Slides

# Results: Avoiding convergence to local minimum during NODE training

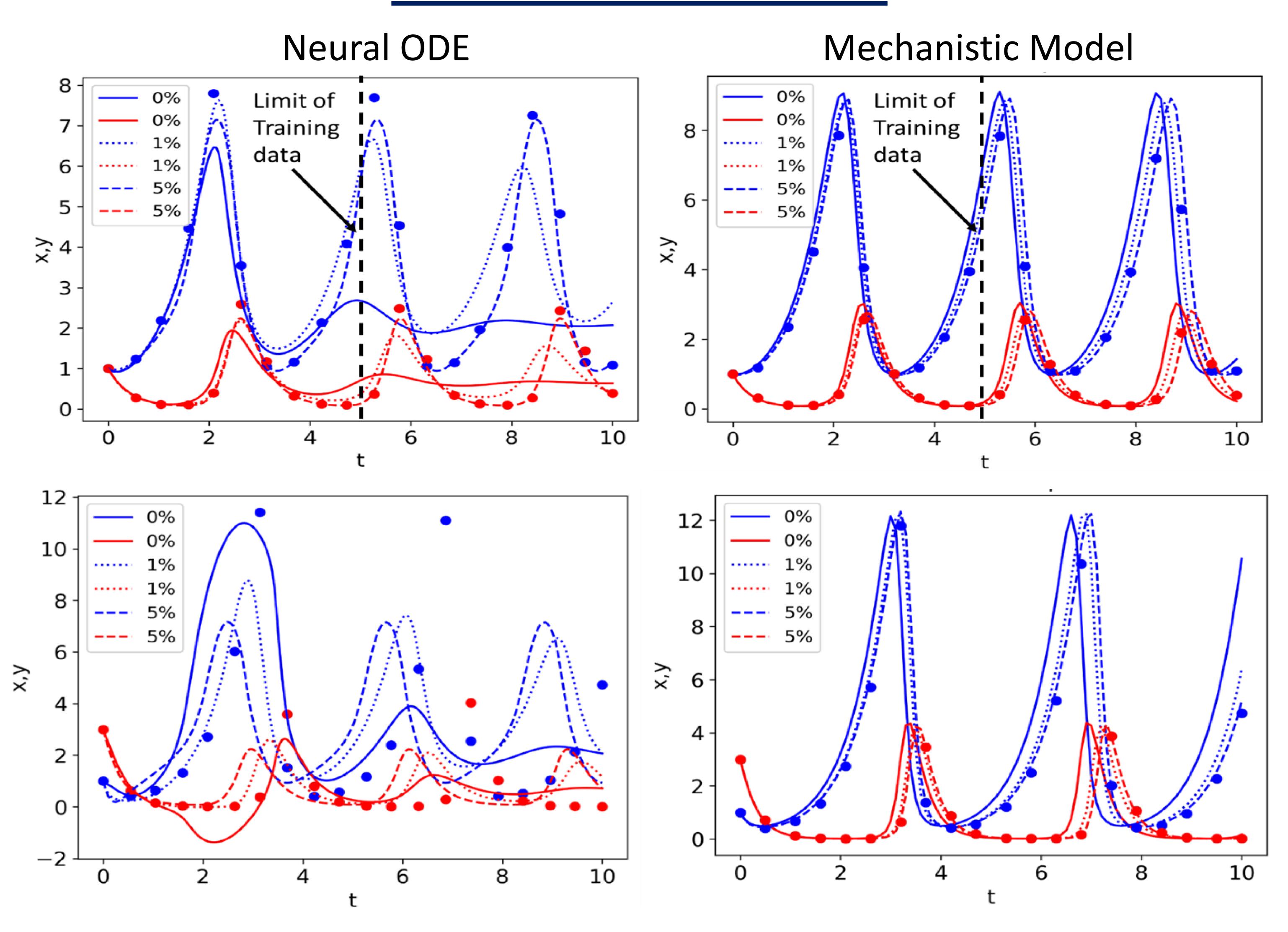




Integration from t = 0 to 5

Integration from  $t = t_o$  to  $t_o + 4\Delta t$  $t_o = \{0, 1\Delta t, 2\Delta t, 3\Delta t, ..., t_f\}$ 

## Results: Extrapolation of NODE vs Mechanistic ODE



# Results: indirect approach can fit ODE models with many parameters

Simulation of mechanistic ODEs with true parameters

Simulation of mechanistic ODE; parameters fitted with noisy data via indirect approach

